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1. Reductions

Definition 1.

SAT (Boolean satisfiable) problem: SAT problem for a given Boolean formulae tries to answer, whether there exists a truth assignment making the Boolean formula true. In other words, can we assign the variables of a given Boolean formula such a way as to make the formula evaluate to true.

Cook-Levin Theorem: Cook-Levin Theorem states that SAT problem is NP-complete. So there exist a poly-time computable function f s.t $\{x \in L \text{ iff } f(x) = \phi_x \text{ is satisfiable}\}$, where L is the language in NP i.e. $L \leq_p SAT$

Definition 2.

Levin-reduction: The above $L \leq_p SAT$ reduction not only satisfies $\{x \in L \text{ iff } \phi_x \text{ is satisfiable}\}$, but it also provides an efficient way of transforming a certificate for x to a satisfying assignment for ϕ_x and vice versa.

Observation 1.

It is easy (poly-time) to find a certificate for a x (where $x \in L$) from a satisfying assignment of ϕ_x . Such reductions are known as Levin reduction.

Observation 2.

There is a one-to-one onto map between certificates of x and certificates of ϕ_x .

Suppose u is a certificate of x

$$\Psi_x : u \longrightarrow (u, g(x, u)) \text{ and } u \longleftarrow (u, z)$$

where, z is the snapshot of the Turing machine.

It provides a one-to-one and onto map between the set of certificates for x and the set of satisfying assignments for ϕ_x , (So they are of same size)

Definition 3.

Parsimonious reductions: Reductions satisfying Observation 2 are known as Parsimonious reductions.

Cook-Levin(Restated): For every language $L \in NP$, there is a parsimonious reduction from L to SAT.

Definition 4.

Running Time of a TM: Let $T : N \rightarrow N$ and $f : \{0, 1\}^* \rightarrow \{0, 1\}^*$. We say that a TM M computes f in time $T(n)$ iff on every input $x \in \{0, 1\}^*$, $M(x) = f(x)$ and number of basic operations (number of times M applies a rule from the truth table) of M on input x is bounded by $T(|x|)$.

Fact: ϕ_x is of size $O(T(|x|) \log T(|x|))$

2. Independent/Stable set

Definition 5.

Independent set of a graph G is a set of vertices of G such that no two of which are adjacent in G .

The problem of finding existence of independent set of size k can be formulated as

$$INDSET = \{ \langle G, k \rangle : \exists S \subseteq V(G) \text{ s.t. } |S| = k \text{ and } \forall u, v \in S, (u, v) \notin E(G) \}$$

Theorem 1.

INDSET problem is NP-Complete

Proof. To show that INDSET problem is NP-Complete, we have to show INDSET is both NP and NP-Hard.

1. INDSET is NP.

Suppose somebody has given a certificate that contains a set of vertices, in polynomial time we can verify whether the number of vertices given in the certificate is equal to k and also verify whether two vertices are not adjacent.

2. INDSET is NP-Hard.

We will prove this by doing a polynomial time reduction from 3-SAT to INDSET (i.e. $3\text{-SAT} \leq_p \text{INDSET}$).

Suppose ϕ is in 3-CNF. Our goal is to define poly time computable map

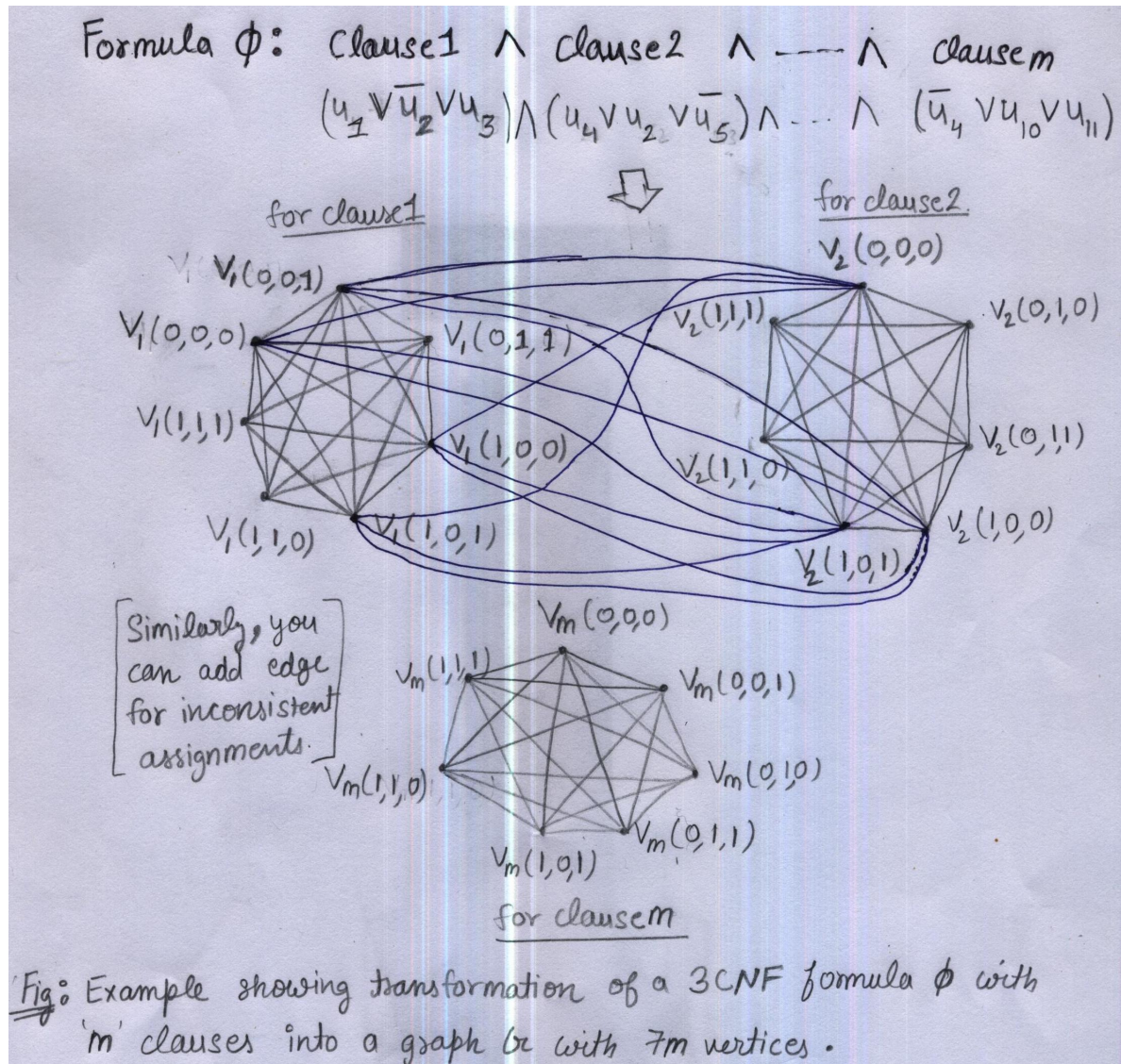
$$f: \phi \longrightarrow f(\phi) = \langle G, k \rangle \text{ s.t. } \phi \in 3\text{-SAT} \text{ iff } \langle G, k \rangle \in \text{INDSET}$$

Let m be the number of clauses in ϕ . The graph G is defined as follows: we associate a cluster of 7 vertices in G with each clause of ϕ . The vertices in a cluster associated with a clause C , corresponds to the 7 possible satisfying partial assignments to the three variables on which C depends (If C depends on less than three variables, then we repeat one of the partial assignment). Inside a cluster we connect all pair of vertices and put an edge between two vertices of G if they correspond to inconsistent partial assignments. The below figure shows the transformation.

The transformation from ϕ to G can be done in polynomial time.

We are now showing that ϕ is satisfiable iff G has an independent set of size m .

Case 1: Suppose ϕ has a satisfying assignment u . We are going to define $S \subseteq V(G)$ of size m . For each clause C of ϕ , add a vertex in S that correspond to the restrictions of the assignment u to the variables C depends. Since



no two vertices of S correspond to inconsistent assignments. Hence S is an independent set of size m .

Case 2: Suppose G has an independent set of size m . We are going to define assignment u of ϕ . For every $i \in [n]$ (n is the number of variables in ϕ), if there is a vertex in S , whose partial assignment gives a value a to u_i , then set $u_i = a$, otherwise $u_i = 0$. Since S is an independent set, each variable u_i can take at most one value. Since we put all the edges within each cluster, S can have at most a single vertex from each cluster. So $|S| = m$, implies S has exactly one vertex from every cluster which is the satisfying assignment. Hence it satisfies all of ϕ clauses. $\square$

Homework 1.

Prove or disprove that the above reduction is Parsimonious Reduction.

3. 0/1 Integer Programming

Definition 6.

0/1 IP is a mathematical feasibility(optimization) program in which variables can take only 0 or 1 values.

Input: set of linear constraints with rational coefficients.

$$Ax \leq b \text{ s.t. } x \in \{0,1\}$$

Task: Check whether there is a 0/1 assignment to the x -variables s.t. all the given constraints are satisfied.

Theorem 2.

0/1 Integer Programming is NP-Complete.

Proof. To prove this we have to show,

1. 0/1 IP is NP.

If somebody gives a certificate that contains 0/1 assignment of variables, then we can verify whether provided certificate is satisfiable or not, in polynomial time.

2. 0/1 IP is NP-Hard.

We will prove this by doing a polynomial time reduction from 3-SAT to 0/1 IP (i.e $3\text{-SAT} \leq_p 0/1 \text{ IP}$).

Let $\phi = C_1 \wedge C_2 \wedge \dots \wedge C_m$, and let the variables in the 3-SAT formula be $x_1, x_2, \dots, x_n$ and their corresponding variables $z_1, z_2, \dots, z_n$ in our 0/1 IP.

For each clause C_i (e.g. $x_1 \vee x_2 \vee \neg x_3$) we have a constraint (like: $z_1 + z_2 + (1 - z_3) \geq 1$). To satisfy this inequality we must set $z_1 = 1$ or $z_2 = 1$ or $z_3 = 0$, which means $x_1 = \text{true}$ or $x_2 = \text{true}$ or $x_3 = \text{false}$ in the corresponding truth assignment.

□

4. Remark on Factoring

FACT₁ := $\{ \langle N, L, U \rangle : \text{if there exist a number } \in [L, U] \text{ that divides } N \}$

The FACT₁ problem is NP-Complete.

FACT₂ := $\{ \langle N, L, U \rangle : \text{if there is a prime } p \text{ in the interval } [L, U] \text{ that divides } N \}$

Note: We can factor a number using $O(\sqrt{N})$ trials division, but the representation of N have $\log N$ bits, hence it is an exponential time algorithm.

FACT₂ is in NP. The current best algorithm for FACT₂ runs in time $2^{O((\log N)^{1/3}(\log \log N)^{2/3})}$.

5. Subset Sum Problem

Definition 7.

Given a (multi)set X of integers and an integer k , does there exist a non-empty subset of X whose sum is k .

SUBSET-SUM = $\{ \langle X, k \rangle \mid X = \{x_1, x_2, \dots, x_n\} \text{ and } \exists A \subseteq [n] \text{ s.t. } \sum_{i \in A} x_i = k \}$

Input: Given $X = \{x_1, x_2, \dots, x_n\}$ and k

Task: Check if $\exists A \subseteq [n] \text{ s.t. } \sum_{i \in A} x_i = k$

Theorem 3.

SUBSET-SUM Problem is NP-complete.

Proof. To prove this we have to show,

1. SUBSET-SUM Problem is NP.

If somebody gives a certificate that contains a subset of X , then we can verify whether provided certificate is subset of X and sum up to k in polynomial time.

2. SUBSET-SUM Problem is NP-Hard.

We prove this by showing $3\text{-SAT} \leq_p \text{SUBSET-SUM}$

(a) Let we have l variables $\{v_1, \dots, v_l\}$ and m clauses $\{c_1, \dots, c_m\}$.

(b) For each variables v_i create a number t_i and f_i of $(l + m)$ digits.

i. The i^{th} digit of t_i and f_i is equal to 1.

ii. For all j , $l + 1 \leq j \leq l + m$

A. $t_{i,j} = 1$, if v_i is in clause c_{j-l} , 0 otherwise.

B. $f_{i,j} = 1$ if $\neg x_i$ is in clause c_{j-l} , 0 otherwise.

Example:

$$(x_1 \vee x_2 \vee x_3) \wedge (\overline{x_1} \vee \overline{x_2} \vee x_3) \wedge (\overline{x_1} \vee x_2 \vee \overline{x_3}) \wedge (x_1 \vee \overline{x_2} \vee x_3)$$

Number	i			j			
	1	2	3	1	2	3	4
t_1	1	0	0	1	0	0	1
f_1	1	0	0	0	1	1	0
t_2	0	1	0	1	0	1	0
f_2	0	1	0	0	1	0	1
t_3	0	0	1	1	1	0	1
f_3	0	0	1	0	0	1	0

(c) For each clause c_j , create x_j and y_j of length $(l + m)$ and initialize it to 0.

i. assign $x_{j,l+j}$ and $y_{j,l+j}$ to 1.

(d) Create sum s , of length $(l + m)$

i. For j , $1 \leq j \leq n$, $s_j = 1$

ii. For j , $l + 1 \leq j \leq l + m$, $s_j = 3$

Number	i			j			
	1	2	3	1	2	3	4
x_1	0	0	0	1	0	0	0
y_1	0	0	0	1	0	0	0
x_2	0	0	0	0	1	0	0
y_2	0	0	0	0	1	0	0
x_3	0	0	0	0	0	1	0
y_3	0	0	0	0	0	1	0
x_4	0	0	0	0	0	0	1
y_4	0	0	0	0	0	0	1

□

6. Cryptosystem Based on SUBSET-SUM Problem.

Merkle-Hellman is a public/asymmetric key encryption proposed by **Ralph Merkle and Martin Hellman** in 1978.

Definition 8.

Public Key : It is made available to everyone via a publicly accessible repository or directory.

Definition 9.

Private Key : The Private Key must remain confidential to its respective owner.

Private Key :

1. A superincreasing sequence $e = \langle e_1, e_2, \dots, e_n \rangle$ s.t. $\forall i \in n, e_i > \sum_{j=1}^{i-1} e_j$
2. Pick a random integer m s.t $m > \sum_{i=1}^n e_i$.
3. A number w that is relatively prime to m . i.e $\exists w'$ s.t. $w' \cdot w \equiv 1 \pmod{m}$.

Public Key :

A sequence of numbers $(h_1, h_2, \dots, h_n)$ s.t. $h_i \equiv w \cdot e_i \pmod{m}$

Encryption :

Let $X = (x_1, x_2, \dots, x_n)$ is the plain(original) message which a user wants to send. It is a 0-1 string.

To encrypt n-bit message X , calculate Ciphertext $C = \sum_i h_i \cdot x_i$, which is the encrypted message and is send to the receiver.

Decryption

Receiver receives C . In order to decrypt a Ciphertext C , a receiver has to find the message bits x_i .

Receiver have $C = \sum_{i=1}^n h_i \cdot x_i$

$$w' \cdot C \equiv \sum_{i=1}^n w' \cdot h_i \cdot x_i$$

$$\equiv \sum_i w' \cdot w \cdot e_i \cdot x_i \pmod{m} \quad [\text{because } h_i \equiv w \cdot e_i \pmod{m}]$$

$$\equiv \sum_i e_i \cdot x_i \pmod{m} \quad [\text{because } w' \cdot w \equiv 1 \pmod{m}]$$

$$= \sum_i e_i \cdot x_i \quad [\text{because of super-increasing sequence}]$$

Receiver knows $\sum_{i=1}^n e_i \cdot x_i = D(\text{say})$ using the private key. Now, this problem is in the same form of SUBSET-SUM Problem and it is easy to solve because X is a superincreasing sequence. If numbers in the set are superincreasing then the problem is solvable in polynomial time using simple greedy algorithm (Reference [3]).

1. Take largest element from e , let e_k
2. If $e_k > D$ then $x_k = 0$, otherwise $x_k = 1$.
3. Subtract $(x_k \cdot e_k)$ from D and remove e_k from e and continue to step-1, until you get X .

References

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- [1] S.ARORA and B.BARAK Computational Complexity: A Modern Approach, Cambridge University Press, 2009
 - [2] Michael Sipser "Introduction to Theory of Computation", Cengage Learning
 - [3] Shamir, Adi (1984). "A polynomial-time algorithm for breaking the basic Merkle - Hellman cryptosystem". Information Theory, IEEE Transactions on 30 (5): 699704