Computational Complexity Theory

Lecture 10: NL = co-NL;
Polynomial Hierarchy

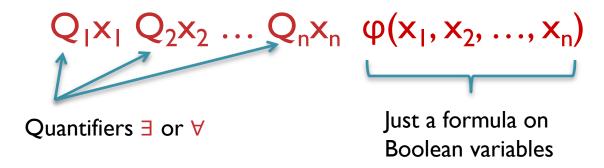
Department of Computer Science, Indian Institute of Science

Recap: PSPACE-completeness

- Recall, to define completeness of a complexity class, we need an appropriate notion of a <u>reduction</u>.
- What kind of reductions will be suitable is guided by <u>a</u> <u>complexity question</u>, like a comparison between the complexity class under consideration & another class.
- Is P = PSPACE? ...use poly-time Karp reduction!
- Definition. A language L' is *PSPACE-hard* if for every L in PSPACE, L \leq_p L'. Further, if L' is in PSPACE then L' is *PSPACE-complete*.

Recap: PSPACE-complete problem

• Definition. A quantified Boolean formula (QBF) is a formula of the form



 A QBF is either <u>true</u> or <u>false</u> as all variables are quantified. This is unlike a formula we've seen before where variables were <u>unquantified/free</u>.

Recap: PSPACE-complete problem

 Definition. TQBF is the set of <u>true</u> quantified Boolean formulas.

Theorem. TQBF is PSPACE-complete.

Recap: PSPACE-complete problem

 Definition. TQBF is the set of <u>true</u> quantified Boolean formulas.

Theorem. TQBF is PSPACE-complete.

- Theorem. (Shamir 1990; Lund, Fortnow, Karloff, Nisan 1990) IP = PSPACE.
- IP or *Interactive Proof* is a grand generalization of NP proof.

Recap: NL-completeness

- Recall again, to define completeness of a complexity class, we need an appropriate notion of a <u>reduction</u>.
- What kind of reductions will be suitable is guided by <u>a</u> <u>complexity question</u>, like a comparison between the complexity class under consideration & another class.
- Is L = NL? ...poly-time (Karp) reductions are much too powerful for L.
- We need to define a suitable 'log-space' reduction.

Recap: Log-space reductions

$$(x, i) \xrightarrow{\text{Log-space TM}} f(x)_i$$

- Issue: A log-space TM may not have enough space to write down the whole output f(x) in one shot.
- Solution: Have the log-space TM output a bit of f(x).
- Definition: A function $f: \{0, 1\}^* \rightarrow \{0, 1\}^*$ is <u>implicitly log-space computable</u> if
 - 1. $|f(x)| \le |x|^c$ for some constant c,
 - 2. The following two languages are in L:

$$L_f = \{(x, i) : f(x)_i = I\}$$
 and $L'_f = \{(x, i) : i \le |f(x)|\}$

Recap: Log-space reductions

$$(x, i) \xrightarrow{\text{Log-space TM}} f(x)_i$$

- Issue: A log-space TM may not have enough space to write down the whole output f(x) in one shot.
- Solution: Have the log-space TM output a bit of f(x).

• Definition: A language L_1 is <u>log-space reducible</u> to a language L_2 , denoted $L_1 \le_l L_2$, if there's an implicitly log-space computable function f such that

$$x \in L_1 \iff f(x) \in L_2$$

Recap: Log-space reductions

$$(x, i) \xrightarrow{\text{Log-space TM}} f(x)_i$$

- Issue: A log-space TM may not have enough space to write down the whole output f(x) in one shot.
- Solution: Have the log-space TM output a bit of f(x).

- Claim: If $L_1 \le_l L_2$ and $L_2 \le_l L_3$ then $L_1 \le_l L_3$.
- Claim: If $L_1 \leq_l L_2$ and $L_2 \in L$ then $L_1 \in L$.

Recap: NL-completeness

 Definition: A language L is NL-complete if L ∈ NL and for every L' ∈ NL, L' is log-space reducible to L.

PATH = $\{(G,s,t): G \text{ is a digraph having a path from } s \text{ to } t\}$.

Theorem: PATH is NL-complete.

 Reachability in DAGs, checking if a digraph is strongly connected, and 2SAT are also NL-complete.

An alternate characterization of NL

- Like NP, it will be useful to have a certificate-verifier kind of definition for the class NL.
- We'll see how it helps in proving NL = co-NL i.e., in showing PATH ∈ NL.

PATH = $\{(G,s,t): G \text{ is a digraph with } \underline{no} \text{ path from } s \text{ to } t\}$

- Like NP, it will be useful to have a certificate-verifier kind of definition for the class NL.
- We'll see how it helps in proving NL = co-NL i.e., in showing PATH ∈ NL.

PATH = $\{(G,s,t): G \text{ is a digraph with } \underline{no} \text{ path from } s \text{ to } t\}$

 Definition.(first attempt) Suppose L is a language, and there's a <u>log-space verifier</u> M & a function q s.t.

$$x \in L \iff \exists u \in \{0,1\}^{q(|x|)} \text{ s.t. } M(x,u) = I$$

Should we define q(|x|) as a log function, meaning $q(|x|) = O(\log |x|)$?

- Like NP, it will be useful to have a certificate-verifier kind of definition for the class NL.
- We'll see how it helps in proving NL = co-NL i.e., in showing PATH ∈ NL.
 - PATH = $\{(G,s,t): G \text{ is a digraph with } \underline{no} \text{ path from } s \text{ to } t\}$
- Definition.(first attempt) Suppose L is a language, and there's a log-space verifier M & a function q s.t.

$$x \in L \iff \exists u \in \{0,1\}^{q(|x|)} \text{ s.t. } M(x,u) = I$$

Should we define q(|x|) as a log function, meaning $q(|x|) = O(\log |x|)$? ... No, that's too restrictive. That will imply $L \in L$.

- Like NP, it will be useful to have a certificate-verifier kind of definition for the class NL.
- We'll see how it helps in proving NL = co-NL i.e., in showing PATH ∈ NL.

PATH = $\{(G,s,t): G \text{ is a digraph with } \underline{no} \text{ path from } s \text{ to } t\}$

 Definition.(first attempt) Suppose L is a language, and there's a log-space verifier M & a poly-function q s.t.

$$x \in L \iff \exists u \in \{0,1\}^{q(|x|)} \text{ s.t. } M(x,u) = I$$

Is it so that $L \in NL$ iff L has such a log-space verifier of the above kind?

- Like NP, it will be useful to have a certificate-verifier kind of definition for the class NL.
- We'll see how it helps in proving NL = co-NL i.e., in showing PATH ∈ NL.

PATH = $\{(G,s,t): G \text{ is a digraph with } \underline{no} \text{ path from } s \text{ to } t\}$

 Definition.(first attempt) Suppose L is a language, and there's a log-space verifier M & a poly-function q s.t.

$$x \in L \iff \exists u \in \{0,1\}^{q(|x|)} \text{ s.t. } M(x,u) = I$$

Is it so that $L \in NL$ iff L has such a log-space verifier of the above kind? Unfortunately not!! Exercise: $L \in NP$ iff L has such a log-space verifier.

- Like NP, it will be useful to have a certificate-verifier kind of definition for the class NL.
- We'll see how it helps in proving NL = co-NL i.e., in showing PATH ∈ NL.

PATH = $\{(G,s,t): G \text{ is a digraph with } \underline{no} \text{ path from } s \text{ to } t\}$

 Definition.(first attempt) Suppose L is a language, and there's a log-space verifier M & a poly-function q s.t.

$$x \in L \iff \exists u \in \{0,1\}^{q(|x|)} \text{ s.t. } M(x,u) = I$$

Solution: Make the certificate <u>read-one</u> as described next...

- Like NP, it will be useful to have a certificate-verifier kind of definition for the class NL.
- We'll see how it helps in proving NL = co-NL i.e., in showing PATH ∈ NL.
 - PATH = $\{(G,s,t): G \text{ is a digraph with } \underline{no} \text{ path from } s \text{ to } t\}$

 Definition. A tape is called a read-one tape if the head moves from left to right and never turns back.

- Like NP, it will be useful to have a certificate-verifier kind of definition for the class NL.
- We'll see how it helps in proving NL = co-NL i.e., in showing PATH ∈ NL.

PATH = $\{(G,s,t): G \text{ is a digraph with } \underline{no} \text{ path from } s \text{ to } t\}$

• Definition. A language L has read-once certificates if there's a log-space verifier M & a poly-function q s.t.

 $x \in L \quad \Longrightarrow \exists u \in \{0,1\}^{q(|x|)} \text{ s.t. } M(x,u) = 1,$

where <u>u</u> is given on a read-once input tape of M.

- Like NP, it will be useful to have a certificate-verifier kind of definition for the class NL.
- We'll see how it helps in proving NL = co-NL i.e., in showing PATH ∈ NL.

PATH = $\{(G,s,t): G \text{ is a digraph with } \underline{no} \text{ path from } s \text{ to } t\}$

Theorem. L ∈ NL iff L has read-once certificates.

- Like NP, it will be useful to have a certificate-verifier kind of definition for the class NL.
- We'll see how it helps in proving NL = co-NL i.e., in showing PATH ∈ NL.
 - PATH = $\{(G,s,t): G \text{ is a digraph with } \underline{no} \text{ path from } s \text{ to } t\}$
- Theorem. L ∈ NL iff L has read-once certificates.
- Proof. Suppose L ∈ NL. Let N be an NTM that decides L. Think of a verifier M that on input (x, u) simulates N on input x by using u as the nondeterministic choices of N. Clearly |u| = poly(|x|)...

- Like NP, it will be useful to have a certificate-verifier kind of definition for the class NL.
- We'll see how it helps in proving NL = co-NL i.e., in showing PATH ∈ NL.

PATH = $\{(G,s,t): G \text{ is a digraph with } \underline{no} \text{ path from } s \text{ to } t\}$

- Theorem. L ∈ NL iff L has read-once certificates.
- Proof. (contd.) ...as $G_{N,x}$ has poly(|x|) configurations. M scans u from left to right without moving its head backward. So, u is a read-once certificate satisfying,

```
x \in L \implies \exists u \in \{0,1\}^{poly(|x|)} \text{ s.t. } M(x,u) = I
```

- Like NP, it will be useful to have a certificate-verifier kind of definition for the class NL.
- We'll see how it helps in proving NL = co-NL i.e., in showing PATH ∈ NL.

PATH = $\{(G,s,t): G \text{ is a digraph with } \underline{no} \text{ path from } s \text{ to } t\}$

- Theorem. L ∈ NL iff L has read-once certificates.
- Proof. (contd.) Suppose L has read-once certificates, and M be a log-space verifier s.t.

```
x \in L \quad \Longrightarrow \exists u \in \{0,1\}^{q(|x|)} \text{ s.t. } M(x,u) = 1.
```

- Like NP, it will be useful to have a certificate-verifier kind of definition for the class NL.
- We'll see how it helps in proving NL = co-NL i.e., in showing PATH ∈ NL.
 - PATH = $\{(G,s,t): G \text{ is a digraph with } \underline{no} \text{ path from } s \text{ to } t\}$
- Theorem. L ∈ NL iff L has read-once certificates.
- Proof. (contd.) Now, think of an NTM N that on input x starts simulating M. It guesses the bits of u as and when required during the simulation. As u is readonce for M, there's no need for N to store u.

- Like NP, it will be useful to have a certificate-verifier kind of definition for the class NL.
- We'll see how it helps in proving NL = co-NL i.e., in showing PATH ∈ NL.

```
PATH = \{(G,s,t): G \text{ is a digraph with } \underline{no} \text{ path from } s \text{ to } t\}
```

- Theorem. L ∈ NL iff L has read-once certificates.
- Proof. (contd.) So, N is a log-space NTM deciding L.

Class co-NL

 Definition. A language L is in co-NL if T∈ NL. L is co-NL-complete if L ∈ co-NL and for every L' ∈ co-NL, L' is log-space reducible to L.

```
PATH = \{(G,s,t): G \text{ is a digraph with } no \text{ path from } s \text{ to } t\}
```

Obs. PATH is co-NL-complete under log-space reduction.

Class co-NL

 Definition. A language L is in co-NL if T∈ NL. L is co-NL-complete if L ∈ co-NL and for every L' ∈ co-NL, L' is log-space reducible to L.

```
PATH = \{(G,s,t): G \text{ is a digraph with } no \text{ path from } s \text{ to } t\}
```

• Obs. PATH is co-NL-complete under log-space reduction.

 Obs. If a language L' log-space reduces to a language in NL then L' ∈ NL. (Homework) So, if PATH ∈ NL then NL = co-NL.

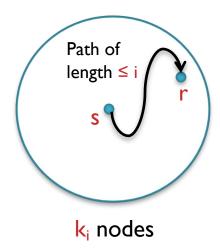
• Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.

- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. It is sufficient to show that there's a log-space verifier M & a poly-function q s.t.

```
x \in PATH \implies \exists u \in \{0,1\}^{q(|x|)} \text{ s.t. } M(x,u) = 1, where u is given on a read-once input tape of M.
```

 Let us focus on forming a <u>read-once certificate u</u> that convinces a verifier that there's no path from s to t...

- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. x = (G,s,t). Let m be the number of nodes in G.
 Let k_i = no. of nodes reachable from s by a path of length at most i in G.



- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. x = (G,s,t). Let m be the number of nodes in G.
 Let k_i = no. of nodes reachable from s by a path of length at most i in G.
 - Read-once certificate u is of the form $(u_1, u_2, ..., u_m, v)$, where u_i 's and v are strings s.t.
 - (I) reading until $(u_1, u_2, ... u_i)$ in a read-once fashion, M knows correctly the value of k_i .

- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. x = (G,s,t). Let m be the number of nodes in G.
 Let k_i = no. of nodes reachable from s by a path of length at most i in G.

Read-once certificate u is of the form $(u_1, u_2, ..., u_m, v)$, where u_i 's and v are strings s.t.

(I) reading until $(u_1, u_2, ... u_i)$ in a read-once fashion, M knows correctly the value of k_i . So, after reading $(u_1, u_2, ... u_m)$, M knows k_m , the number of nodes reachable from s.

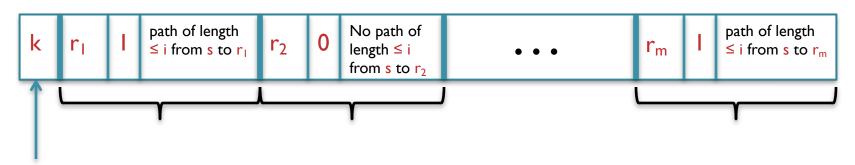
- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. x = (G,s,t). Let m be the number of nodes in G.
 Let k_i = no. of nodes reachable from s by a path of length at most i in G.

Read-once certificate u is of the form $(u_1, u_2, ..., u_m, v)$, where u_i 's and v are strings s.t.

- (I) reading until $(u_1, u_2, ... u_i)$ in a read-once fashion, M knows correctly the value of k_i . So, after reading $(u_1, u_2, ... u_m)$, M knows k_m , the number of nodes reachable from s.
- (2) v then convinces M (which already knows k_m) that t is not one of the k_m vertices reachable from s.

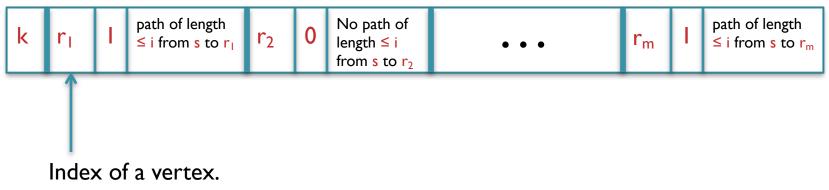
- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. We'll design u_i assuming that $u_1, ..., u_{i-1}$ have already been constructed and M knows k_{i-1} . Let r_1 , ..., r_m be the nodes of G s.t. $r_1 < r_2 < < r_m$. Then,

- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. We'll design u_i assuming that u_1, \ldots, u_{i-1} have already been constructed and M knows k_{i-1} . Let r_1 , ... r_m be the nodes of G s.t. $r_1 < r_2 < \ldots < r_m$. Then, u_i looks like:



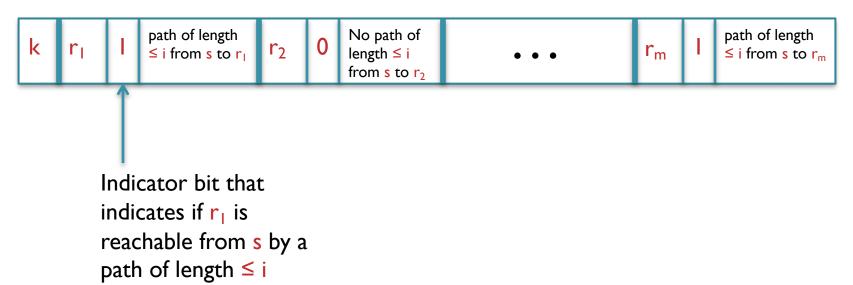
The claimed value of k_i . O(log m) bits required.

- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. We'll design u_i assuming that u_1, \ldots, u_{i-1} have already been constructed and M knows k_{i-1} . Let r_1 , ... r_m be the nodes of G s.t. $r_1 < r_2 < \ldots < r_m$. Then, u_i looks like:

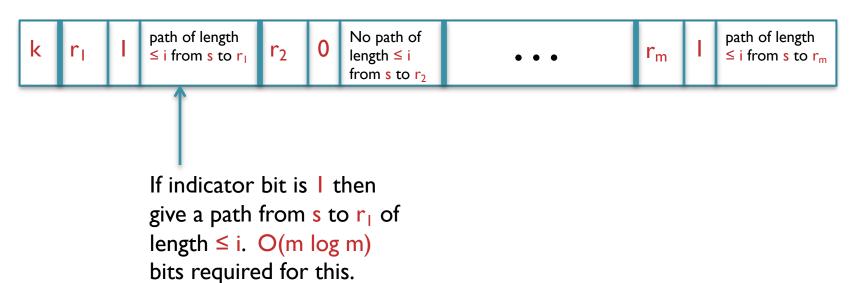


O(log m) bits required.

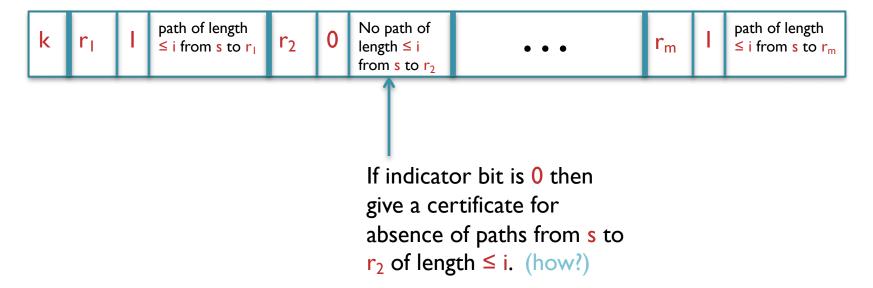
- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. We'll design u_i assuming that u_1, \ldots, u_{i-1} have already been constructed and M knows k_{i-1} . Let r_1 , ... r_m be the nodes of G s.t. $r_1 < r_2 < \ldots < r_m$. Then, u_i looks like:



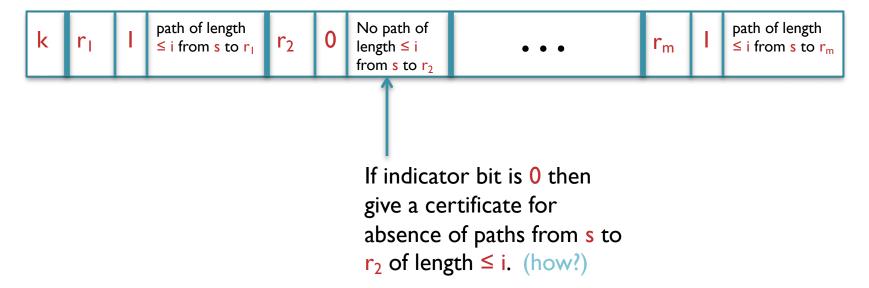
- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. We'll design u_i assuming that u_1, \ldots, u_{i-1} have already been constructed and M knows k_{i-1} . Let r_1 , ... r_m be the nodes of G s.t. $r_1 < r_2 < \ldots < r_m$. Then, u_i looks like:



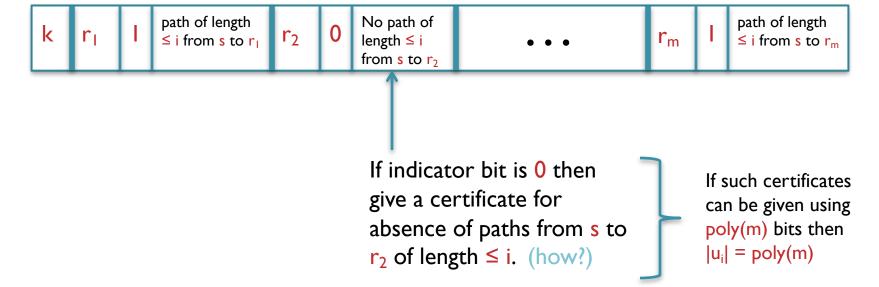
- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. We'll design u_i assuming that u_1, \ldots, u_{i-1} have already been constructed and M knows k_{i-1} . Let r_1 , ... r_m be the nodes of G s.t. $r_1 < r_2 < \ldots < r_m$. Then, u_i looks like:



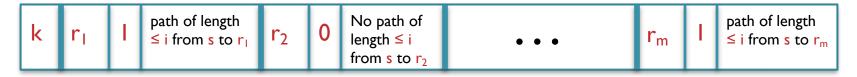
- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. We'll design u_i assuming that u_1, \ldots, u_{i-1} have already been constructed and M knows k_{i-1} . Let r_1 , ... r_m be the nodes of G s.t. $r_1 < r_2 < \ldots < r_m$. Then, u_i looks like:



- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. We'll design u_i assuming that u_1, \ldots, u_{i-1} have already been constructed and M knows k_{i-1} . Let r_1 , ... r_m be the nodes of G s.t. $r_1 < r_2 < \ldots < r_m$. Then, u_i looks like:

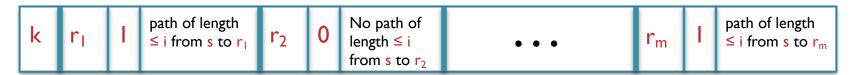


- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. We'll design u_i assuming that u_1, \ldots, u_{i-1} have already been constructed and M knows k_{i-1} . Let r_1 , ... r_m be the nodes of G s.t. $r_1 < r_2 < \ldots < r_m$. Then, u_i looks like:



- While reading u_i , M's work tape remembers the following info:
 - $I.k_{i-1}$ and k,
 - 2. the last read index of a vertex r_i

- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. We'll design u_i assuming that u_1, \ldots, u_{i-1} have already been constructed and M knows k_{i-1} . Let r_1 , ... r_m be the nodes of G s.t. $r_1 < r_2 < \ldots < r_m$. Then, u_i looks like:

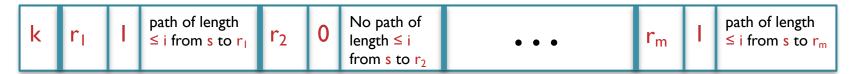


While reading u_i, M's work tape remembers the following info:
 The moment M encounters a new vertex index r, it checks immediately if r > r_i. This ensures that M is not

fooled by repeating info about the same vertex in ui.

- $l.k_{i-1}$ and k,
- 2. the last read index of a vertex r_i

- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. We'll design u_i assuming that u_1, \ldots, u_{i-1} have already been constructed and M knows k_{i-1} . Let r_1 , ... r_m be the nodes of G s.t. $r_1 < r_2 < \ldots < r_m$. Then, u_i looks like:

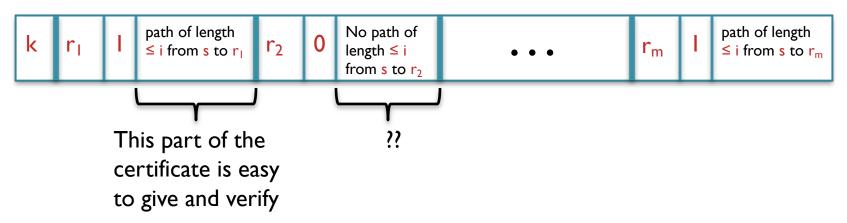


• While reading u_i, M's work tape remembers the following info:

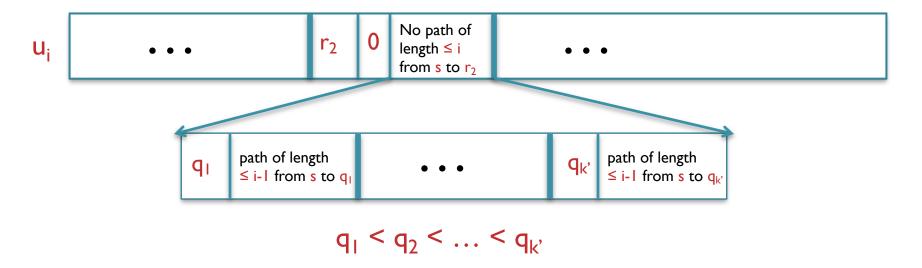
While reading u_i, M keeps a count of the number of indicator bits that are I and finally checks if this number is k.

- $I.k_{i-1}$ and k,
- 2. the last read index of a vertex r_i

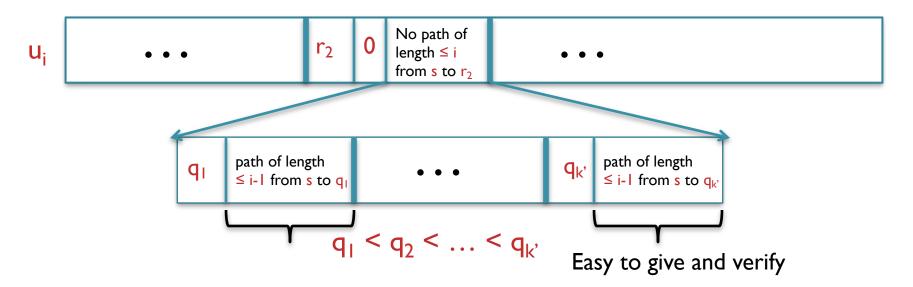
- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. We'll design u_i assuming that u_1, \ldots, u_{i-1} have already been constructed and M knows k_{i-1} . Let r_1 , ... r_m be the nodes of G s.t. $r_1 < r_2 < \ldots < r_m$. Then, u_i looks like:



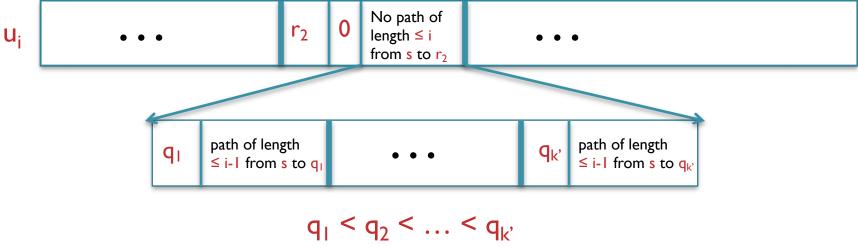
- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. Recall, M knows $k_{i-1} = k'$ (say) while reading u_i .



- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. Recall, M knows $k_{i-1} = k'$ (say) while reading u_i .

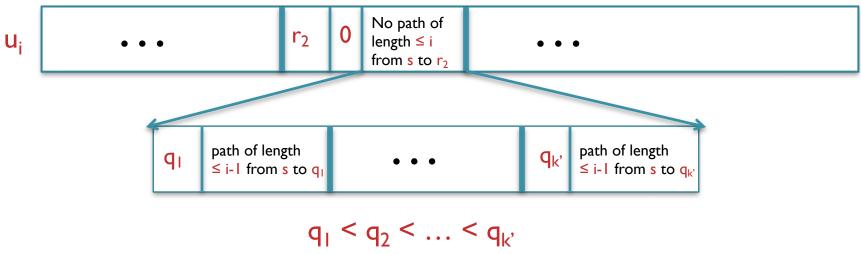


- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. Recall, M knows $k_{i-1} = k'$ (say) while reading u_i .



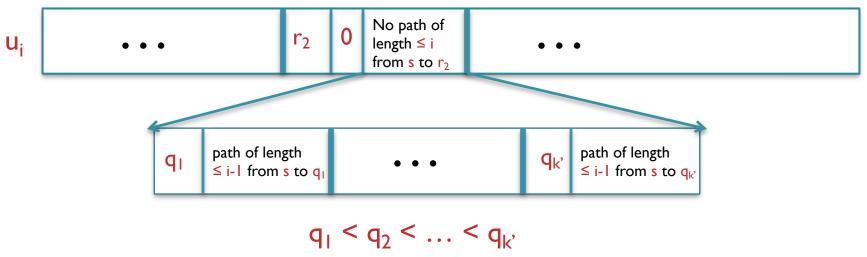
While reading the 'No path...r₂' part of u_i, M remembers the last q_j read and checks that the next q
 > q_i. This ensures M is not fooled by repeating q's.

- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. Recall, M knows $k_{i-1} = k'$ (say) while reading u_i .



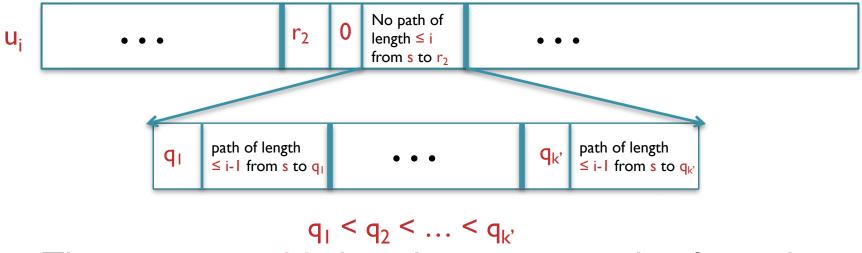
• For every $j \in [1,k_{i-1}]$, after verifying the path of length $\leq i$ -I from s to q_j , M checks that r_2 is not adjacent to q_i by looking at G's adjacency matrix.

- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. Recall, M knows $k_{i-1} = k'$ (say) while reading u_i .



• At the end of reading the 'No path... r_2 ' part, M checks that the number of q's read is exactly k_{i-1} .

- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. Recall, M knows $k_{i-1} = k'$ (say) while reading u_i .



• This convinces M that there is no path of length \leq i from s to r_2 . Length of the 'No path... r_2 ' part of u_i is $O(m^2 \log m)$.

- Theorem. (Immerman-Szelepcsenyi 1987) PATH ∈ NL.
- Proof. So, after reading $(u_1, ..., u_m)$, the verifier M knows k_m , the number of vertices reachable from s.
- The v part of the certificate u is similar to the 'No path... r_2 ' part of u_i described before. The details here are easy to fill in (homework).

 We stress again that M is able to verify nonexistence of a path between s and t by reading u once from left to right and never moving its head backward.

• Hence, both PATH and $\overline{PATH} \in NL \subseteq SPACE((log n)^2)$

by Savitch's theorem.

Polynomial Hierarchy

Problems between NP & PSPACE

 There are decision problems that don't appear to be captured by nondeterminism alone (i.e., with a single
 ∃ or ∀ quantifier), unlike problems in NP and co-NP.

• Example.

```
Eq-DNF = \{(\varphi,k): \varphi \text{ is a } DNF \text{ and } \underline{\text{there's}} \text{ a } DNF \psi \}
of size \leq k that is \underline{\text{equivalent}} \text{ to } \varphi \}
```

 Two Boolean formulas on the same input variables are equivalent if their evaluations agree on every assignment to the variables.

Problems between NP & PSPACE

 There are decision problems that don't appear to be captured by nondeterminism alone (i.e., with a single
 ∃ or ∀ quantifier), unlike problems in NP and co-NP.

• Example.

```
Eq-DNF = \{(\phi,k): \phi \text{ is a DNF and there's a DNF } \psi \}
of size \leq k that is equivalent to \phi
```

• Is Eq-DNF in NP? ...if we give a DNF ψ as a certificate, it is not clear how to efficiently verify that ψ and ϕ are equivalent. (W.I.o.g. $k \le \text{size of } \phi$.)

• Definition. A language L is in \sum_2 if there's a polynomial function q(.) and a poly-time TM M (the "verifier") s.t.

```
x \in L \iff \exists u \in \{0,1\}^{q(|x|)} \ \forall v \in \{0,1\}^{q(|x|)} \ \text{s.t.} \ M(x,u,v) = 1.
```

• Definition. A language L is in \sum_{2} if there's a polynomial function q(.) and a poly-time TM M (the "verifier") s.t. $x \in L \iff \exists u \in \{0,1\}^{q(|x|)} \forall v \in \{0,1\}^{q(|x|)} \text{ s.t. } M(x,u,v) = 1.$

- Obs. Eq-DNF is in \sum_{2} .
- Proof. Think of u as another DNF ψ and v as an assignment to the variables. Poly-time TM M checks if ψ has size $\leq k$ and $\phi(v) = \psi(v)$.

• Definition. A language L is in \sum_{2} if there's a polynomial function q(.) and a poly-time TM M (the "verifier") s.t. $x \in L \iff \exists u \in \{0,1\}^{q(|x|)} \forall v \in \{0,1\}^{q(|x|)} \text{ s.t. } M(x,u,v) = 1.$

- Obs. Eq-DNF is in \sum_{2} .
- Proof. Think of u as another DNF ψ and v as an assignment to the variables. Poly-time TM M checks if ψ has size $\leq k$ and $\varphi(v) = \psi(v)$.

• Remark. (Masek 1979) Even if φ is given by its truth-table, the problem (i.e., DNF-MCSP) is NP-complete.

• Definition. A language L is in \sum_{2} if there's a polynomial function q(.) and a poly-time TM M (the "verifier") s.t. $x \in L \iff \exists u \in \{0,1\}^{q(|x|)} \forall v \in \{0,1\}^{q(|x|)} \text{ s.t. } M(x,u,v) = 1.$

Another example.

```
Succinct-SetCover = \{(\phi_1,...,\phi_m,k): \phi_i\} are DNFs and there's an S \subseteq [m] of size \leq k s.t. \bigvee_{i \in S} \phi_i is a tautology
```

• Definition. A language L is in \sum_{2} if there's a polynomial function q(.) and a poly-time TM M (the "verifier") s.t. $x \in L \iff \exists u \in \{0,1\}^{q(|x|)} \forall v \in \{0,1\}^{q(|x|)} \text{ s.t. } M(x,u,v) = 1.$

• Obs. (Homework) Succinct-SetCover is in \sum_{2} .

• Definition. A language L is in \sum_{2} if there's a polynomial function q(.) and a poly-time TM M (the "verifier") s.t. $x \in L \implies \exists u \in \{0,1\}^{q(|x|)} \forall v \in \{0,1\}^{q(|x|)} \text{ s.t. } M(x,u,v) = 1.$

- Obs. (Homework) Succinct-SetCover is in \sum_{2} .
- Other natural problems in PH: "Completeness in the Polynomial-Time Hierarchy: A Compendium" by Schaefer and Umans (2008).

• Definition. A language L is in \sum_2 if there's a polynomial function q(.) and a poly-time TM M (the "verifier") s.t.

```
x \in L \iff \exists u \in \{0,1\}^{q(|x|)} \ \forall v \in \{0,1\}^{q(|x|)} \ \text{s.t.} \ M(x,u,v) = 1.
```

• Obs. $P \subseteq NP \subseteq \sum_{2}$.

• Definition. A language L is in \sum_{i} if there's a polynomial function q(.) and a poly-time TM M (the "verifier") s.t.

```
x \in L \iff \exists u_1 \in \{0,1\}^{q(|x|)} \quad \forall u_2 \in \{0,1\}^{q(|x|)} \quad Q_i u_i \in \{0,1\}^{q(|x|)}
s.t. M(x,u_1,...,u_i) = I,
```

where Q_i is \exists or \forall if i is odd or even, respectively.

• Obs. $\sum_{i} \subseteq \sum_{i+1}$ for every i.

Polynomial Hierarchy

• Definition. A language L is in \sum_i if there's a polynomial function q(.) and a poly-time TM M (the "verifier") s.t.

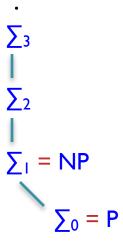
$$x \in L \iff \exists u_1 \in \{0,1\}^{q(|x|)} \quad \forall u_2 \in \{0,1\}^{q(|x|)} \quad Q_i u_i \in \{0,1\}^{q(|x|)}$$

s.t. $M(x,u_1,...,u_i) = I$,

where Q_i is \exists or \forall if i is odd or even, respectively.

• Definition. (Meyer & Stockmeyer 1972)

$$PH = \bigcup_{i \in N} \sum_{i}$$
.



Class \prod_i

- Definition. $\prod_i = co-\sum_i = \{L : \overline{L} \in \sum_i \}.$
- Obs. A language L is in \prod_i if there's a polynomial function q(.) and a poly-time TM M (the "verifier") s.t.

```
x \in L \iff \forall u_1 \in \{0,1\}^{q(|x|)} \exists u_2 \in \{0,1\}^{q(|x|)} \ Q_i u_i \in \{0,1\}^{q(|x|)}
s.t. M(x,u_1,...,u_i) = I,
```

where Q_i is \forall or \exists if i is odd or even, respectively.

Class \prod_i

- Definition. $\prod_i = co \sum_i = \{ L : \overline{L} \in \sum_i \}.$
- Obs. A language L is in \prod_i if there's a polynomial function q(.) and a poly-time TM M (the "verifier") s.t.

$$x \in L \iff \forall u_1 \in \{0,1\}^{q(|x|)} \exists u_2 \in \{0,1\}^{q(|x|)} \ Q_i u_i \in \{0,1\}^{q(|x|)}$$

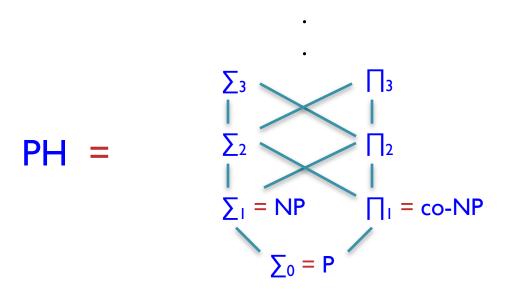
s.t. $M(x,u_1,...,u_i) = I$,

where Q_i is \forall or \exists if i is odd or even, respectively.

• Obs. $\sum_{i} \subseteq \prod_{i+1} \subseteq \sum_{i+2}$.

Polynomial Hierarchy

• Obs. PH =
$$\bigcup_{i \in \mathbb{N}} \sum_{i \in \mathbb{N}} \prod_{i \in \mathbb{N}} \prod_{i}$$
.



Polynomial Hierarchy

- Claim. PH ⊆ PSPACE.
- Proof. Similar to the proof of TQBF ∈ PSPACE.

