Computational Complexity Theory

Lecture 5: NTMs; Class co-NP & EXP

Department of Computer Science, Indian Institute of Science

Recap: Search version of NP

- Recall: A language $L \subseteq \{0,1\}^*$ is in NP if
 - > There's a poly-time verifier M and poly. function p s.t.
 - $> x \in L$ iff there's a $u \in \{0,1\}^{p(|x|)}$ s.t M(x, u) = 1.
- Search version of L: Given an input $x \in \{0,1\}^*$, find a $u \in \{0,1\}^{p(|x|)}$ such that M(x,u) = 1, if such a u exists.
- Example: Given a 3CNF ϕ , find a satisfying assignment for ϕ if such an assignment exists.

Recap: Decision versus Search

- Is the search version of an NP-problem more difficult than the corresponding decision version?
- Theorem. Let $L \subseteq \{0,1\}^*$ be NP-complete. Then, the search version of L can be solved in poly-time if and only if the decision version can be solved in poly-time.

w.r.t any verifier M!

Recap: Decision versus Search

- Is search equivalent to decision for every NP problem?
- Theorem. (Bellare & Goldwasser 1994) If EE ≠ NEE then there's a language in NP for which search does not reduce to decision.

• Definition. A language $L_1 \subseteq \{0,1\}^*$ is <u>polynomial-time</u> (Karp or many-one) reducible to a language $L_2 \subseteq \{0,1\}^*$ if there's a polynomial time computable function f s.t.

$$x \in L_1 \iff f(x) \in L_2$$

• Definition. A language $L_1 \subseteq \{0,1\}^*$ is <u>polynomial-time</u> (Cook or Turing) reducible to a language $L_2 \subseteq \{0,1\}^*$ if there's a TM that decides L_1 in poly-time using polymany calls to a "subroutine" for deciding L_2 .

• Definition. A language $L_1 \subseteq \{0,1\}^*$ is <u>polynomial-time</u> (Karp or many-one) reducible to a language $L_2 \subseteq \{0,1\}^*$ if there's a polynomial time computable function f s.t.

$$x \in L_1 \iff f(x) \in L_2$$

• Definition. A language $L_1 \subseteq \{0,1\}^*$ is <u>polynomial-time</u> (Cook or Turing) reducible to a language $L_2 \subseteq \{0,1\}^*$ if there's a TM that decides L_1 in poly-time using polymany calls to a "subroutine" for deciding L_2 .

• Definition. A language $L_1 \subseteq \{0,1\}^*$ is <u>polynomial-time</u> (Karp or many-one) reducible to a language $L_2 \subseteq \{0,1\}^*$ if there's a polynomial time computable function f s.t.

$$x \in L_1 \iff f(x) \in L_2$$

• Definition. A language $L_1 \subseteq \{0,1\}^*$ is <u>polynomial-time</u> (Cook or Turing) reducible to a language $L_2 \subseteq \{0,1\}^*$ if there's a TM that decides L_1 in poly-time using polymany calls to a "subroutine" for deciding L_2 .

• Definition. A language $L_1 \subseteq \{0,1\}^*$ is <u>polynomial-time</u> (Karp or many-one) reducible to a language $L_2 \subseteq \{0,1\}^*$ if there's a polynomial time computable function f s.t.

$$x \in L_1 \iff f(x) \in L_2$$

• Definition. A language $L_1 \subseteq \{0,1\}^*$ is <u>polynomial-time</u> (Cook or Turing) reducible to a language $L_2 \subseteq \{0,1\}^*$ if there's a TM that decides L_1 in poly-time using polymany calls to a "subroutine" for deciding L_2 .

Homework: Read about Levin reduction



- A nondeterministic Turing machine is like a deterministic Turing machines but with two transition functions.
- It is formally defined by a tuple $(\Gamma, Q, \delta_0, \delta_1)$. It has a special state q_{accept} in addition to q_{start} and q_{halt} .

- A nondeterministic Turing machine is like a deterministic Turing machines but with two transition functions.
- It is formally defined by a tuple $(\Gamma, Q, \delta_0, \delta_1)$. It has a special state q_{accept} in addition to q_{start} and q_{halt} .
- At every step of computation, the machine applies one of two functions δ_0 and δ_1 arbitrarily.



also called *nondeterministically*

- A nondeterministic Turing machine is like a deterministic Turing machines but with two transition functions.
- It is formally defined by a tuple $(\Gamma, Q, \delta_0, \delta_1)$. It has a special state q_{accept} in addition to q_{start} and q_{halt} .
- At every step of computation, the machine applies one of two functions δ_0 and δ_1 arbitrarily.



this is different from *randomly*

- A nondeterministic Turing machine is like a deterministic Turing machines but with two transition functions.
- It is formally defined by a tuple $(\Gamma, Q, \delta_0, \delta_1)$. It has a special state q_{accept} in addition to q_{start} and q_{halt} .
- At every step of computation, the machine applies one of two functions δ_0 and δ_1 arbitrarily.
- Unlike DTMs, NTMs are not intended to be physically realizable (because of the arbitrary nature of application of the transition functions).

- Definition. An NTM M <u>accepts</u> a string $x \in \{0,1\}^*$ iff on input x there <u>exists</u> a sequence of applications of the transition functions δ_0 and δ_1 (beginning from the start configuration) that makes M reach q_{accept} .
- Defintion. An NTM M <u>decides</u> a language $L \subseteq \{0,1\}^*$ if
 - ➤ M accepts x ← x∈L
 - \triangleright On every sequence of applications of the transition functions on input x, M either reaches q_{accept} or q_{halt} .

- Definition. An NTM M accepts a string $x \in \{0,1\}^*$ iff on input x there **exists** a sequence of applications of the transition functions δ_0 and δ_1 (beginning from the start configuration) that makes M reach q_{accept} .
- Defintion. An NTM M decides a language $L \subseteq \{0,1\}^*$ if
 - ➤ M accepts x ← x∈L
 - \triangleright On every sequence of applications of the transition functions on input x, M either reaches q_{accept} or q_{halt} .

remember in this course we'll always be dealing with TMs that halt on every input.

- Definition. An NTM M accepts a string $x \in \{0,1\}^*$ iff on input x there **exists** a sequence of applications of the transition functions δ_0 and δ_1 (beginning from the start configuration) that makes M reach q_{accept} .
- Defintion. An NTM M decides L in T(|x|) time if
 - ➤ M accepts x ← x∈L
 - \triangleright On <u>every sequence</u> of applications of the transition functions on input x, M either reaches q_{accept} or q_{halt} within T(|x|) steps of computation.

Class NTIME

• Definition. A language L is in NTIME(T(n)) if there's an NTM M that decides L in c. T(n) time on inputs of length n, where c is a constant.

- Definition. A language L is in NTIME(T(n)) if there's an NTM M that decides L in c. T(n) time on inputs of length n, where c is a constant.
- Theorem. NP = U NTIME (n^c).
 Proof sketch: Let L be a language in NP. Then, there's a poly-time verifier M s.t,

 $x \in L$ $\Longrightarrow \exists u \in \{0,1\}^{p(|x|)}$ s.t. M(x, u) = I

 Definition. A language L is in NTIME(T(n)) if there's an NTM M that decides L in c. T(n) time on inputs of length n, where c is a constant.

• Theorem. NP = $\bigcup_{c>0}$ NTIME (n^c).

Proof sketch: Let L be a language in NP. Then, there's a poly-time verifier M s.t,

$$x \in L$$
 $\Longrightarrow \exists u \in \{0,1\}^{p(|x|)} \text{ s.t. } M(x,u) = I$

Think of an NTM M' that on input x, at first <u>guesses</u> a $u \in \{0,1\}^{p(|x|)}$ by applying δ_0 and δ_1 nondeterministically

 Definition. A language L is in NTIME(T(n)) if there's an NTM M that decides L in c. T(n) time on inputs of length n, where c is a constant.

Theorem. NP = U NTIME (n^c).
 Proof sketch: Let L be a language in NP. Then, there's a poly-time verifier M s.t,

 $x \in L$ $\Longrightarrow \exists u \in \{0,1\}^{p(|x|)} \text{ s.t. } M(x,u) = I$

.... and then simulates M on (x, u) to verify M(x, u) = 1.

 Definition. A language L is in NTIME(T(n)) if there's an NTM M that decides L in c. T(n) time on inputs of length n, where c is a constant.

```
• Theorem. NP = \bigcup_{c>0} NTIME (n<sup>c</sup>).
Proof sketch: Let L be in NTIME (n<sup>c</sup>). Then, there's an NTM M' that decides L in p(n) = O(n<sup>c</sup>) time. (|x| = n)
```

 Definition. A language L is in NTIME(T(n)) if there's an NTM M that decides L in c. T(n) time on inputs of length n, where c is a constant.

• Theorem. NP = $\bigcup_{c>0}$ NTIME (n^c). Proof sketch: Let L be in NTIME (n^c). Then, there's an NTM M' that decides L in p(n) = O(n^c) time. (|x| = n) Think of a verifier M that takes x and u $\in \{0,1\}^{p(n)}$ as input,

 Definition. A language L is in NTIME(T(n)) if there's an NTM M that decides L in c. T(n) time on inputs of length n, where c is a constant.

• Theorem. NP = $\bigcup_{c>0}$ NTIME (nc).

Proof sketch: Let L be in NTIME (nc). Then, there's an NTM M' that decides L in p(n) = $O(n^c)$ time. (|x| = n)

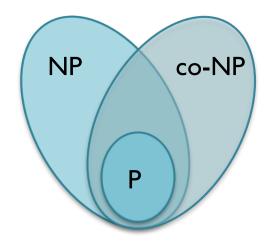
Think of a verifier M that takes x and u $\in \{0,1\}^{p(n)}$ as input, and simulates M' on x with u as the sequence of choices for applying δ_0 and δ_1 .

Class co-NP and EXP

- Definition. For every L ⊆ {0,1}* let L̄ = {0,1}* \ L.
 A language L is in co-NP if L̄ is in NP.
- Example. SAT = $\{\phi : \phi \text{ is } \underline{not} \text{ satisfiable}\}$.

- Definition. For every $L \subseteq \{0,1\}^*$ let $\overline{L} = \{0,1\}^* \setminus L$. A language L is in co-NP if \overline{L} is in NP.
- Example. SAT = $\{\phi : \phi \text{ is } \underline{not} \text{ satisfiable}\}$.
- Note: co-NP is <u>not</u> complement of NP. Every language in P is in both NP and co-NP.

- Definition. For every $L \subseteq \{0,1\}^*$ let $\overline{L} = \{0,1\}^* \setminus L$. A language L is in co-NP if \overline{L} is in NP.
- Example. SAT = $\{\phi : \phi \text{ is } \underline{not} \text{ satisfiable}\}$.



- Definition. For every $L \subseteq \{0,1\}^*$ let $\overline{L} = \{0,1\}^* \setminus L$. A language L is in co-NP if \overline{L} is in NP.
- Example. SAT = $\{\phi : \phi \text{ is } \underline{not} \text{ satisfiable}\}$.
- Note: SAT is Cook reducible to SAT. But, there's a fundamental difference between the two problems that is captured by the fact that SAT is not known to be Karp reducible to SAT. In other words, there's no known poly-time verification process for SAT.

```
x \in L \iff \exists u \in \{0,1\}^{p(|x|)} \text{ s.t. } M(x,u) = I
```

```
x \in L \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x, u) = I

x \in \overline{L} \Longrightarrow \forall u \in \{0,1\}^{p(|x|)} s.t. M(x, u) = 0
```

```
x \in L \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I x \in \overline{L} \Longrightarrow \forall u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = 0 x \in \overline{L} \Longrightarrow \forall u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u)
```

```
x \in L \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I

x \in \overline{L} \Longrightarrow \forall u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = 0

x \in \overline{L} \Longrightarrow \forall u \in \{0,1\}^{p(|x|)} s.t. \overline{M}(x,u) = I

\Longrightarrow \overline{M} is a poly-time TM
```

```
x \in L \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I x \in \overline{L} \Longrightarrow \forall u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = 0 x \in \overline{L} \Longrightarrow \forall u \in \{0,1\}^{p(|x|)} s.t. \overline{M}(x,u) = I is in co-NP
```

• Recall, a language $L \subseteq \{0,1\}^*$ is in NP if there's a poly-time verifier M such that

```
x \in L \Longrightarrow \exists u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = I

x \in \overline{L} \Longrightarrow \forall u \in \{0,1\}^{p(|x|)} s.t. M(x,u) = 0

x \in \overline{L} \Longrightarrow \forall u \in \{0,1\}^{p(|x|)} s.t. \overline{M}(x,u) = I
```

• Definition. A language $L \subseteq \{0,1\}^*$ is in co-NP if there's a polynomial function p and a poly-time TM M such that

$$x \in L$$
 $\forall u \in \{0,1\}^{p(|x|)}$ s.t. $M(x, u) = I$ for NP this was \exists

co-NP-completeness

- Definition. A language L' $\subseteq \{0,1\}^*$ is co-NP-complete if
 - L' is in co-NP
 - Every language L in co-NP is polynomial-time (Karp) reducible to L'.

• Theorem. SAT is co-NP-complete.

co-NP-completeness

- Definition. A language $L' \subseteq \{0,1\}^*$ is co-NP-complete if
 - L' is in co-NP
 - Every language L in co-NP is polynomial-time (Karp) reducible to L'.

• Theorem. SAT is co-NP-complete.

Proof. Let $L \in \text{co-NP}$. Then $\overline{L} \in \text{NP}$

- Definition. A language $L' \subseteq \{0,1\}^*$ is co-NP-complete if
 - L' is in co-NP
 - Every language L in co-NP is polynomial-time (Karp) reducible to L'.

Theorem. SAT is co-NP-complete.

Proof. Let
$$L \in \text{co-NP}$$
. Then $\overline{L} \in \text{NP}$ $\Longrightarrow \overline{L} \leq_{D} \text{SAT}$

- Definition. A language L' $\subseteq \{0,1\}^*$ is co-NP-complete if
 - L' is in co-NP
 - Every language L in co-NP is polynomial-time (Karp) reducible to L'.

• Theorem. SAT is co-NP-complete.

Proof. Let
$$L \in \text{co-NP}$$
. Then

$$\Rightarrow \overline{\mathsf{L}} \leq_{\mathsf{D}} \mathsf{SAT}$$

$$\Rightarrow \overline{L} \leq_{p} \overline{SAT}$$

$$\Rightarrow L \leq_{p} \overline{SAT}$$

- Definition. A language L' $\subseteq \{0,1\}^*$ is co-NP-complete if
 - L' is in co-NP
 - Every language L in co-NP is polynomial-time (Karp) reducible to L'.

Theorem. Let

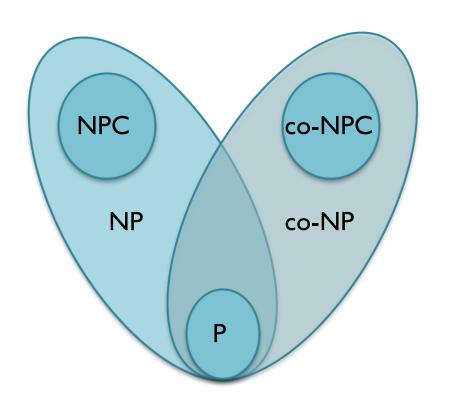
TAUTOLOGY = $\{\phi : \text{ every assignment satisfies } \phi \}$.

TAUTOLOGY is co-NP-complete.

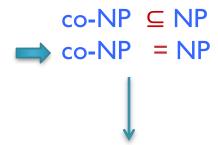
Proof. Similar (homework)

- Definition. A language L' $\subseteq \{0,1\}^*$ is co-NP-complete if
 - L' is in co-NP
 - Every language L in co-NP is polynomial-time (Karp) reducible to L'.

Theorem. If L in NP-complete then L is co-NP-complete
 Proof. Similar (homework)

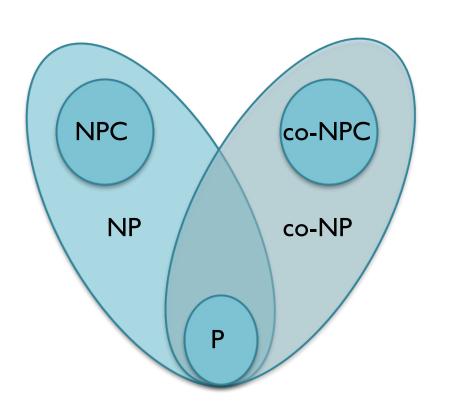


If a co-NP-complete language belongs to NP then

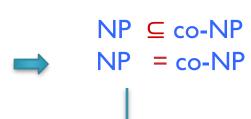


If
$$C_1 \subseteq C_2$$
, then $co-C_1 \subseteq co-C_2$.

Obs.
$$co-(co-C) = C$$
.

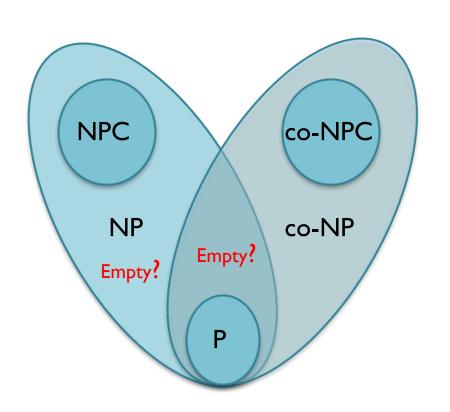


If an NP-complete language belongs to co-NP then

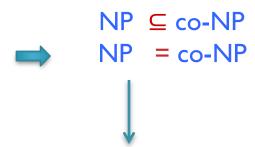


If
$$C_1 \subseteq C_2$$
, then $co-C_1 \subseteq co-C_2$.

Obs.
$$co-(co-C) = C$$
.



If an NP-complete language belongs to co-NP then

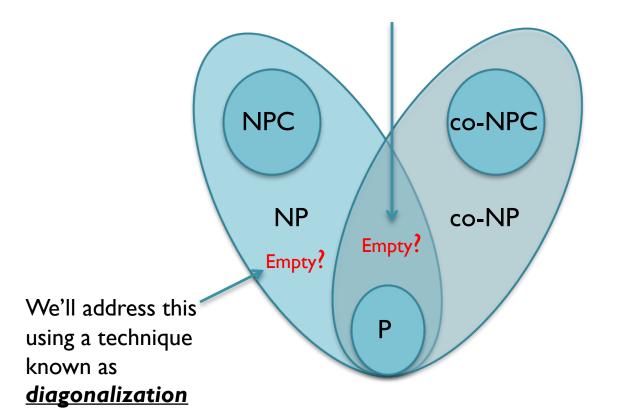


If
$$C_1 \subseteq C_2$$
, then $co-C_1 \subseteq co-C_2$.

Obs.
$$co-(co-C) = C$$
.

We'll revisit this question.

If an NP-complete language belongs to co-NP then



If
$$C_1 \subseteq C_2$$
, then $co-C_1 \subseteq co-C_2$.

Obs.
$$co-(co-C) = C$$
.

Integer factoring.

```
FACT = \{(N, U): \text{ there's a prime in } [U] \text{ dividing } N\}
```

• Claim. FACT \in NP \cap co-NP

• So, FACT is NP-complete implies NP = co-NP.

Integer factoring.
 FACT = {(N, U): there's a prime in [U] dividing N}

- Claim. FACT $\in NP \cap co-NP$
- Proof. FACT ∈ NP : Give p as a certificate. The verifier checks if p is prime (AKS test), I ≤ p ≤ U and p divides N.

Integer factoring.FACT = {(N, U): there's a prime in [U] dividing N}

- Claim. FACT $\in NP \cap co-NP$
- Proof. FACT ∈ NP: Give the complete prime factorization of N as a certificate. The verifier checks the correctness of the factorization, and then checks if none of the prime factors is in [U].

Integer factoring.FACT = {(N, U): there's a prime in [U] dividing N}

- Claim. FACT $\in NP \cap co-NP$
- Proof. FACT ∈ NP: Give the complete prime factorization of N as a certificate. The verifier checks the correctness of the factorization, and then checks if none of the prime factors is in [U].
- Homework: If FACT \in P, then there's a algorithm to find the prime factorization a given n-bit integers in poly(n) time.

Integer factoring.

```
FACT = \{(N, U): \text{there's a prime in } [U] \text{ dividing } N\}
```

• Factoring algorithm. Dixon's randomized algorithm factors an n-bit number in $exp(O(\sqrt{n \log n}))$ time.

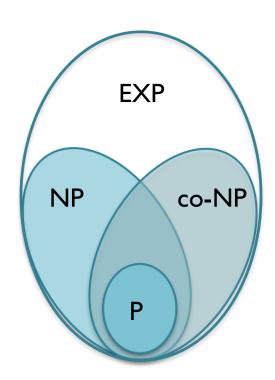
 Definition. Class EXP is the exponential time analogue of class P.

```
EXP = \bigcup_{c \ge 1} DTIME (2^{n^c})
```

 Definition. Class EXP is the exponential time analogue of class P.

$$EXP = \bigcup_{c \ge 1} DTIME (2^{n^c})$$

• Observation. P ⊆ NP ⊆ EXP



 Definition. Class EXP is the exponential time analogue of class P.

$$EXP = \bigcup_{c \ge 1} DTIME (2^{n^c})$$

Observation. P ⊆ NP ⊆ EXP

• Exponential Time Hypothesis. (Impagliazzo & Paturi 1999) Any algorithm for 3-SAT takes $\geq 2^{\delta,n}$ time, where $\delta > 0$ is some fixed constant and n is the no. of variables.

In other words, δ cannot be made arbitrarily close to 0.

 Definition. Class EXP is the exponential time analogue of class P.

$$EXP = \bigcup_{c \ge 1} DTIME (2^{n^c})$$

Observation. P ⊆ NP ⊆ EXP

• Exponential Time Hypothesis. (Impagliazzo & Paturi 1999) Any algorithm for 3-SAT takes $\geq 2^{\delta,n}$ time, where $\delta > 0$ is some fixed constant and n is the no. of variables.

ETH
$$\Rightarrow$$
 P \neq NP

 Definition. Class EXP is the exponential time analogue of class P.

$$EXP = \bigcup_{c \ge 1} DTIME (2^{n^c})$$

Observation. P ⊆ NP ⊆ EXP

• Exponential Time Hypothesis. (Impagliazzo & Paturi 1999) Any algorithm for 3-SAT takes $\geq 2^{\delta,n}$ time, where $\delta > 0$ is some fixed constant and n is the no. of variables.

Homework: Read about Strong Exponential Time Hypothesis (SETH).

Definition. Class EXP is the exponential time analogue of class P.

$$EXP = \bigcup_{c \ge 1} DTIME (2^{n^c})$$

Observation. P ⊆ NP ⊆ EXP

diagonalization

Is P ⊊ EXP?

• Exponential Time Hypothesis. (Impagliazzo & Paturi 1999) Any algorithm for 3-SAT takes $\geq 2^{\delta,n}$ time, where $\delta > 0$ is some fixed constant and n is the no. of variables.