



UMC 201: Data Structures & Algorithms

Lecture I: Course info; Introduction;
Insertion sort; Order notations

Indian Institute of Science

Course Info

- **Course no.:** UMC 201 **Credits:** 3:1
- **Instructors:** Chandan Saha (chandan@iisc)
Sathish Govindarajan (gsat@iisc)
- **Lecture time:** T,Th, 10-11:20 am **Venue:** G-21
- **Teams group:** Will be set up soon.
- **TAs:** Agrim Dewan (agrimdewan@iisc); Sreesankar T M (sreesankar1@iisc), and 4 others.
- **Course homepage:**
<https://www.csa.iisc.ac.in/~chandan/courses/dsa26/home.html>

Course Info

- **Prerequisites:** UENG 101; Mathematical maturity.
- **Primary reference:** Introduction to Algorithms by Cormen, Leiserson, Rivest and Stein. (We'll follow this textbook closely.)
- **Other references:** Data Structures and Algorithm Analysis in C by Weiss; Algorithm Design by Kleinberg & Tardos.

Course Info

- **Number of lectures:** ~25.
- Chandan Saha will teach the first half of the course (until the mid-term exam). Sathish Govindarajan will teach the second half.
- **Lectures:** **Slides** of the first half of the course will be posted on the course homepage. The second half will have **board lectures**; materials will be posted on Teams as and when required.

Course Info

- **Grading policy:** Two class tests - 30% (15% each)
Mid-term exam - 35%
End-term exam - 35%
- **Mid-term exam:** Between Sep 19 – Sep 26
- **Final-term exam:** Between Nov 20 – Dec 2

Class Tests

- Practice problems will be provided in the slides (in the first half) and over Teams (in the second half).
- In a class test, a student will be asked to solve problems (which will be chosen from among the practice problems or slight variants of them).
- There will be multiple sets of question papers for each of the two class tests.
- **Class test duration:** 80 mins, in the class.
- **First test:** Sep 3 (Th). **Second test:** Nov 3 (T)

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- In a class test, a student will be asked to solve problems (which will be chosen from among the practice problems or slight variants of them).
- There will be multiple sets of question papers for each of the two class tests.
- The syllabus for the tests will be announced on the course homepage, over Teams, and in the class.

Mid-term and End-term exams

- Would be 3 hr long written tests.
- **When?** Exact dates will be announced on the course homepage, over Teams, and in the class.
- The problems given in these exams **need not** be from among the practice problems.

Mid-term and End-term exams

- **Mid-term syllabus:** Everything covered before the mid-term exam week.
- **End-term syllabus:** Everything covered after the mid-term and before the end-term exam.

Tutorial sessions?

- If required, we will have doubt-clearing sessions or tutorial sessions. The dates will be announced on the course homepage, over Teams, and in the class.

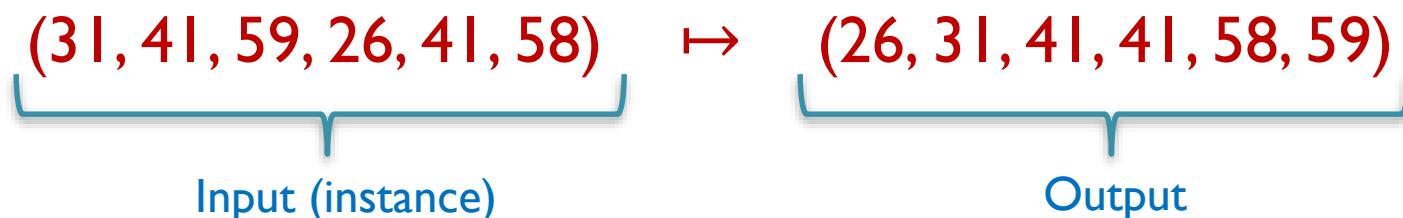
Introduction

What is an algorithm?

- An **algorithm** is a well-defined computational procedure that takes some value, or set of values, as **input** and produces some value, or set of values, as **output** in a *finite amount of time*.
- An algorithm is a tool for solving a well-specified **(computational) problem**.

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- **Example.** (*Sorting problem*) Sort a sequence of numbers into monotonically increasing order.



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- An algorithm **solves** a problem if for every input instance, it halts, and outputs the correct solution.
- An algorithm can be specified as a **pseudocode** or a computer program, or as a hardware design.

What is a pseudocode?

SUM-ARRAY(A, n)

```
1   $sum = 0$   
2  for  $i = 1$  to  $n$   
3       $sum = sum + A[i]$   
4  return  $sum$ 
```

- The above pseudocode (algorithm) takes an array A and a number n as input and returns the sum of the first n values of the array.

Problems and Applications

Problems	Applications
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Topological Sorting	To indicate precedence among events

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We'll discuss all these problems in later lectures.

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Linear Programming	Optimizing an objective, given limited resources and competing constraints
Encryption/Decryption	E-commerce

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- Algorithms to solve these and many other problems are at the core of most technologies used in contemporary computers.

What is a data structure?

- A **data structure** is a way to store and organize data in order to facilitate access and modifications.
- Using appropriate data structures is an important part of algorithm design.
- **Examples of data structures.** Arrays, lists, binary trees, hash tables, etc. We will study these in later lectures.

Techniques for Algorithm Design

- We'll also discuss the following broad techniques for designing and analysing algorithms:
 - Divide-and-Conquer
 - Dynamic Programming
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 - Dynamic Programming
 - Greedy Strategies
 - Amortized Analysis
- These techniques are used to design time efficient algorithms. **Question:** Other than time, what other measure of efficiency can you think of? Memory space.

Insertion Sort:

Our first algorithm

Insertion Sort

- **Sorting problem.** Input is an array of n values $(a_1, \dots, a_n)$. Output a reordering $(a'_1, \dots, a'_n)$ of the input array such that $a'_1 \leq \dots \leq a'_n$.

Insertion Sort

- **Sorting problem.** Input is an array of n values $(a_1, \dots, a_n)$. Output a reordering $(a'_1, \dots, a'_n)$ of the input array such that $a'_1 \leq \dots \leq a'_n$.
- **Insertion sort** works the way you might sort a hand of playing cards.
- **Idea.** Remove one card from the pile and insert it into the correct position.



Insertion Sort: Pseudocode

INSERTION-SORT(A, n)

```
1  for  $i = 2$  to  $n$ 
2       $key = A[i]$ 
3      // Insert  $A[i]$  into the sorted subarray  $A[1 : i - 1]$ .
4       $j = i - 1$ 
5      while  $j > 0$  and  $A[j] > key$ 
6           $A[j + 1] = A[j]$ 
7           $j = j - 1$ 
8       $A[j + 1] = key$ 
```

- Input is an array A of values and the number n of values to sort.

Insertion Sort: Pseudocode

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- **Analyzing** a pseudocode (algorithm) means proving its **correctness** and bounding the resources (which in our case would be **computational time**) that the algorithm requires.

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- **Correctness.** Inside the **for**-loop (Steps 2-8) we assume that the subarray $A[1 : i - 1]$ is already sorted.

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- **Correctness.** Inside the **for**-loop (Steps 2-8) we assume that the subarray $A[1 : i - 1]$ is already sorted. Step 2 stores the value of $A[i]$ in key . This frees up the i^{th} position of A .

Insertion Sort: Pseudocode

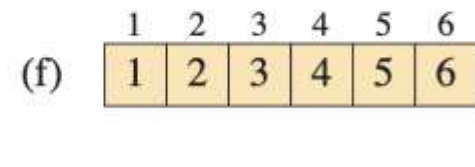
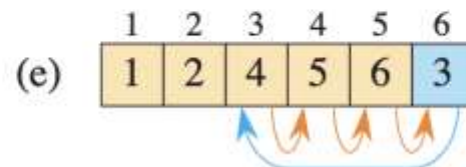
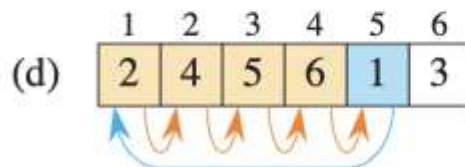
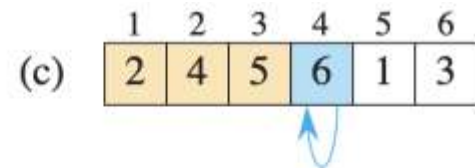
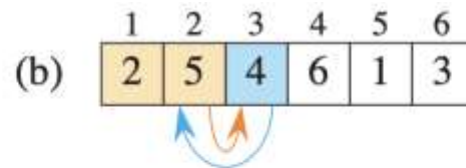
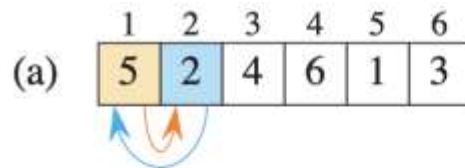
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5      while  $j > 0$  and  $A[j] > key$ 
6           $A[j + 1] = A[j]$ 
7           $j = j - 1$            // At this point  $A[j+1]$  is free
8       $A[j + 1] = key$ 
```

- **Correctness.** The **while**-loop (Steps 5-7) finds the correct position of *key* in $A[1 : i]$ by shifting values to the right. Step 8 then inserts the *key* in the correct position—the $(j + 1)^{th}$ position—once the loop exits.

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- Before we discuss the computational/running time (a.k.a **time complexity**) of the algorithm, we need to specify the **computational model**.
- Our model should be reasonably realistic.

The RAM computational model

- We assume a one-processor **random access memory (RAM)** model of computation.
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- In the RAM model, instructions execute sequentially with no concurrent operations.
- Each **instruction** takes the same amount of time as any other instruction.
- Each **data access** (such as using the value of a variable or storing in a variable) takes the same amount of time as any other data access.

The RAM computational model

- We assume a one-processor **random access memory (RAM)** model of computation.
- The RAM model contains instructions commonly found in real computers: **arithmetic** (addition, subtraction, multiplication, division, etc.), **data movement** (load, store, copy), and **control** (conditional and unconditional branching, subroutine call and return).
- RAM model analyses are usually excellent predictors of performance on actual machines.

Running time or Time complexity

- We'll describe the running time of an algorithm as a function of the size of its input.
- **Input size** depends on the problem being studied:
 - For an array, size is the number of items in it.
 - If the input consists of two integers (as in the integer multiplication problem), then size means the number of bits needed to represent the input.

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 - For an array, size is the number of items in it.
 - If the input consists of two integers (as in the integer multiplication problem), then size means the number of bits needed to represent the input.
- The **running time** on a particular input is the number of instructions or data accesses executed.

Worst-case running time

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 - The worst-case running time gives an upper bound on the running time for any input.
 - For some algorithms, the worst-case occurs fairly often. For example, searching a database when the information is absent.
- We'll be interested in the rate of growth or the **order of growth** of the worst-case running time.

Insertion Sort: Running time

INSERTION-SORT(A, n)

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- The worst-case running time of the **while**-loop (Steps 5-7) is at most $c \cdot i$, where c is a constant.
- So, the worst-case running time of the algorithm is at most $c' \cdot n^2$, where c' is a constant.

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- It's time to introduce the **order notations**...

Order Notations

Asymptotic growth of functions

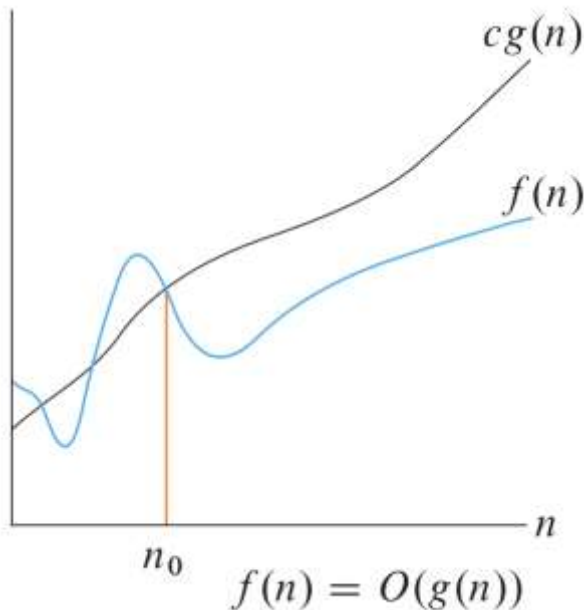
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Asymptotic growth of functions

- We'll be interested in the **asymptotic efficiency** of algorithms.
- That is, we'll be concerned with how the running time of an algorithm grows with the input size.
- We usually consider one algorithm to be **asymptotically more efficient** than another if its worst-case running time has a lower order of growth.
- Usually, an algorithm that is asymptotically more efficient is the best choice for all but small inputs.

Big-oh (O) notation

- *O*-notation describes an asymptotic upper bound.
- **Definition.** For a function $g(n)$,
 $O(g(n)) = \{f(n): \exists \text{ positive constants } c \text{ and } n_0 \text{ s.t.}$
 $0 \leq f(n) \leq cg(n) \text{ for all } n \geq n_0\}.$



Big-oh (O) notation

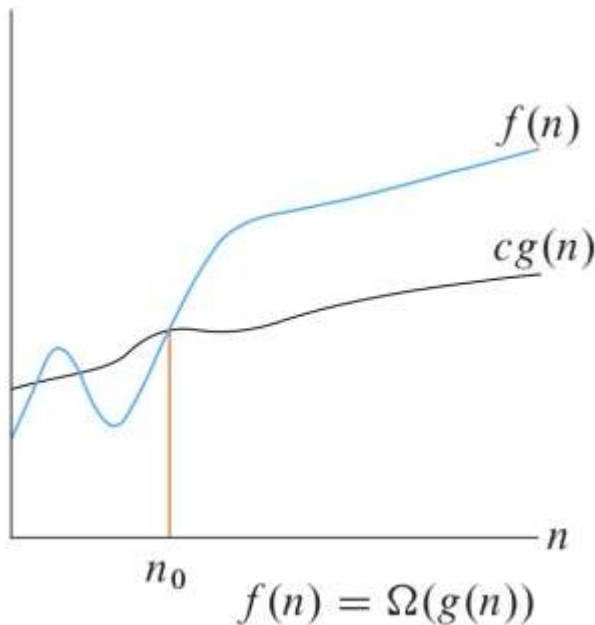
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 $0 \leq f(n) \leq cg(n) \text{ for all } n \geq n_0\}.$
- We usually write “ $f(n) = O(g(n))$ ” and say “ $f(n)$ is big-oh of $g(n)$ ” to mean “ $f(n) \in O(g(n))$ ”.
- **Example.** $4n^2 + 100n + 500 = O(n^2)$. We use asymptotic notations to provide the simplest bound.

Big-omega (Ω) notation

- Ω -notation describes an asymptotic lower bound.

- **Definition.** For a function $g(n)$,

$$\Omega(g(n)) = \{f(n): \exists \text{ positive constants } c \text{ and } n_0 \text{ s.t.} \\ 0 \leq cg(n) \leq f(n) \text{ for all } n \geq n_0\}.$$



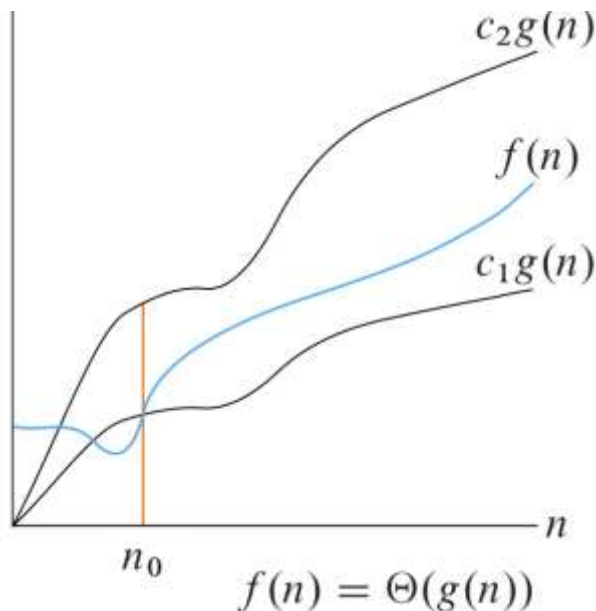
- **Example.** $2n^3 + 4n^2 + 100n + 500 = \Omega(n^3)$.

Theta (Θ) notation

- Θ -notation describes an asymptotically tight bound.

- **Definition.** For a function $g(n)$,

$$\Theta(g(n)) = \{f(n): \exists \text{ positive constants } c_1, c_2 \text{ \& } n_0 \text{ s.t.} \\ 0 \leq c_1 g(n) \leq f(n) \leq c_2 g(n) \text{ for all } n \geq n_0\}.$$



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- **Obs.** For any two functions $f(n)$ and $g(n)$, we have $f(n) = \Theta(g(n))$ if and only if $f(n) = O(g(n))$ and $f(n) = \Omega(g(n))$.

Little-oh (o) notation

- o -notation denotes an upper bound that is not tight.
- **Definition.** For a function $g(n)$, $o(g(n))$ is the set $\{f(n) : \forall \text{ constant } c > 0, \exists \text{ a constant } n_0 > 0 \text{ s.t. } 0 \leq f(n) < cg(n) \text{ for all } n \geq n_0\}$.
- **Example.** $20n = o(n^2)$, but $20n^2 \neq o(n^2)$.

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- The main difference between O and o is: In $f(n) = O(g(n))$, the condition $0 \leq f(n) \leq cg(n)$ holds for some constant $c > 0$, but in $f(n) = o(g(n))$, the condition $0 \leq f(n) < cg(n)$ holds for all $c > 0$.

Little-omega (ω) notation

- ω -notation denotes a lower bound that is not tight.
- **Definition.** For a function $g(n)$, $\omega(g(n))$ is the set $\{f(n) : \forall \text{ constant } c > 0, \exists \text{ a constant } n_0 > 0 \text{ s.t. } 0 \leq cg(n) < f(n) \text{ for all } n \geq n_0\}$.
- **Example.** $\frac{n^2}{20} = \omega(n)$, but $\frac{n^2}{20} \neq \omega(n^2)$.

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- **Example.** $\frac{n^2}{20} = \omega(n)$, but $\frac{n^2}{20} \neq \omega(n^2)$.
- **Obs.** $f(n) = \omega(g(n))$ if and only if $g(n) = o(f(n))$.

Comparing functions

Transitivity:

$f(n) = \Theta(g(n))$ and $g(n) = \Theta(h(n))$ imply $f(n) = \Theta(h(n))$,

$f(n) = O(g(n))$ and $g(n) = O(h(n))$ imply $f(n) = O(h(n))$,

$f(n) = \Omega(g(n))$ and $g(n) = \Omega(h(n))$ imply $f(n) = \Omega(h(n))$,

$f(n) = o(g(n))$ and $g(n) = o(h(n))$ imply $f(n) = o(h(n))$,

$f(n) = \omega(g(n))$ and $g(n) = \omega(h(n))$ imply $f(n) = \omega(h(n))$.

Reflexivity:

$f(n) = \Theta(f(n))$,

$f(n) = O(f(n))$,

$f(n) = \Omega(f(n))$,

Symmetry:

$f(n) = \Theta(g(n))$ if and only if $g(n) = \Theta(f(n))$.

Comparing functions

Transpose symmetry:

$f(n) = O(g(n))$ if and only if $g(n) = \Omega(f(n))$,

$f(n) = o(g(n))$ if and only if $g(n) = \omega(f(n))$.

Practice problems

Practice Problem I

Consider the *searching problem*:

Input: A sequence of n numbers $\langle a_1, a_2, \dots, a_n \rangle$ stored in array $A[1:n]$ and a value x .

Output: An index i such that x equals $A[i]$ or the special value NIL if x does not appear in A .

Write pseudocode for *linear search*, which scans through the array from beginning to end, looking for x . ~~Using a loop invariant, prove that your algorithm is~~

Practice Problem 2

Consider the problem of adding two n -bit binary integers a and b , stored in two n -element arrays $A[0:n-1]$ and $B[0:n-1]$, where each element is either 0 or 1, $a = \sum_{i=0}^{n-1} A[i] \cdot 2^i$, and $b = \sum_{i=0}^{n-1} B[i] \cdot 2^i$. The sum $c = a + b$ of the two integers should be stored in binary form in an $(n+1)$ -element array $C[0:n]$, where $c = \sum_{i=0}^n C[i] \cdot 2^i$. Write a procedure **ADD-BINARY-INTEGERS** that takes as input arrays A and B , along with the length n , and returns array C holding the sum.

Practice Problem 3

Consider sorting n numbers stored in array $A[1:n]$ by first finding the smallest element of $A[1:n]$ and exchanging it with the element in $A[1]$. Then find the smallest element of $A[2:n]$, and exchange it with $A[2]$. Then find the smallest element of $A[3:n]$, and exchange it with $A[3]$. Continue in this manner for the first $n - 1$ elements of A . Write pseudocode for this algorithm, which is known as *selection sort*. ~~What loop invariant does this algorithm maintain? Why does it~~

- Analyze the worst-case running time of *selection sort*.

Practice Problem 4

Bubblesort is a popular, but inefficient, sorting algorithm. It works by repeatedly swapping adjacent elements that are out of order. The procedure BUBBLESORT sorts array $A[1 : n]$.

```
BUBBLESORT( $A, n$ )  
1  for  $i = 1$  to  $n - 1$   
2      for  $j = n$  downto  $i + 1$   
3          if  $A[j] < A[j - 1]$   
4              exchange  $A[j]$  with  $A[j - 1]$ 
```

- **Question.** What is the worst-case running time of BUBBLESORT?

Practice Problem 5

- Is $2^{n+1} = O(2^n)$? Is $2^{2n} = O(2^n)$?
- Prove that $o(g(n)) \cap \omega(g(n))$ is the empty set.
- Show that $k \lg k = \Theta(n)$ implies $k = \Theta(n / \lg n)$.

Practice Problem 6

Let

$$p(n) = \sum_{i=0}^d a_i n^i ,$$

where $a_d > 0$, be a degree- d polynomial in n , and let k be a constant. Use the definitions of the asymptotic notations to prove the following properties.

a. If $k \geq d$, then $p(n) = O(n^k)$.

b. If $k \leq d$, then $p(n) = \Omega(n^k)$.

c. If $k = d$, then $p(n) = \Theta(n^k)$.

d. If $k > d$, then $p(n) = o(n^k)$.

e. If $k < d$, then $p(n) = \omega(n^k)$.

Practice Problem 7

Indicate, for each pair of expressions (A, B) in the table below whether A is O , o , Ω , ω , or Θ of B . Assume that $k \geq 1$, $\epsilon > 0$, and $c > 1$ are constants. Write your answer in the form of the table with “yes” or “no” written in each box.

	A	B	O	o	Ω	ω	Θ
a.	$\lg^k n$	n^ϵ					
b.	n^k	c^n					
c.	$\sqrt{n}$	$n^{\sin n}$					
d.	2^n	$2^{n/2}$					
e.	$n^{\lg c}$	$c^{\lg n}$					
f.	$\lg(n!)$	$\lg(n^n)$					

$$\lg n = \log_2 n$$