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 - Theoretical use mainly in stochastic/mixture models. But wide practical use. Coming Soon.



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- Many other Examples: k-means Clustering. How about k-median? [Discussion later.]



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- How does one pick such a random matrix? Dependence. Also proof of length-preserving property is hard because of the orthonormal requirement.



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- Upper bound: If $\mathbf{v} \cdot \mathbf{u_1} = \sum_{j=1}^d (v_j u_{1j})$ is the sum of d independent Gaussians; means and variances add up. So, $\mathbf{v} \cdot \mathbf{u_1} \sim N(0, |\mathbf{v}|^2)$; thus, whp, $|\mathbf{v} \cdot \mathbf{u_1}| \leq c|\mathbf{v}|$. Note that $c|\mathbf{v}| \approx c|\mathbf{v}| |\mathbf{u_1}|/\sqrt{d}$, so this is an "equator" like bound why?



Random Projection Theorem

Theorem 1 Let f be as above. There is a constant c > 0 such that for $\epsilon \in (0, 1)$,

$$\forall \mathbf{v} \in \mathbf{R}^d : \Pr \underbrace{\left(\left| |f(\mathbf{v})| \ - \ \sqrt{k} |\mathbf{v}| \right| \ \geq \varepsilon \sqrt{k} |\mathbf{v}| \right)}_{|f(\mathbf{v})| \approx_\varepsilon \sqrt{k} |\mathbf{v}|} \leq 3e^{-ck\varepsilon^2},$$

where the probability is taken over the random draws of vectors $\mathbf{u_i}$ used to construct f.

Theorem 2 For any $0 < \varepsilon < 1$ and any integer n, let $k \ge \frac{3}{c\varepsilon^2} \ln n$ for c as in Theorem 1. Suppose $\mathbf{v_1}, \mathbf{v_2}, \dots, \mathbf{v_n}$ is any set of n points.

$$\Pr\left(\forall i, j \in \{1, 2, \dots, n\} \left| f(\mathbf{v_i}) - f(\mathbf{v_j}) \right| \approx_{\varepsilon} \sqrt{k} \left| \mathbf{v_i} - \mathbf{v_j} \right| \right) \ge 1 - \frac{2}{n}.$$



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- Advantage of Linearity of f: Estimate distance between two points $\mathbf{v_1}, \mathbf{v_2} \in \mathbf{R}^d$ is whp $(1 \pm \varepsilon) \frac{1}{\sqrt{k}}$ times distance between $f(\mathbf{v_1})$ and $f(\mathbf{v_2})$, since $f(\mathbf{v_1} \mathbf{v_2}) = f(\mathbf{v_1}) f(\mathbf{v_2})$.

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- Many other random projections are now known. For example, the u_i can be taken as ±1 vectors. Intuitively, if d is large, then v · u_i behaves as if it is a Gaussian r.v. But for small d, we need more care to argue this.



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Proof of Theorem 1

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- Let $\beta = \varepsilon \sqrt{k}$. Pr $\left(|f(\mathbf{v})| \approx_{\varepsilon} \sqrt{k} \right) =$ Pr $\left(|f(\mathbf{v})| \in [\sqrt{k} - \beta, \sqrt{k} + \beta] \right) \ge 1 - e^{-c\beta^2} = 1 - e^{-ck\varepsilon^2}$.



Theorem 2

Union Bound: $O(n^2)$ pairs. Prob of failure for each is at most $e^{-ck\varepsilon^2}$. So with $k \in \Omega(\ln n/\varepsilon^2)$, the failure probability is driven down to $< 1/n^2...$

Very Important: Exponential in k failure prob means we need k to grow only logarithmically.

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- How about k—median clustering: Minimize sum of distances to cluster centers?

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- Will see that "distance-based" clustering can do this if inter-mean separation is $\Omega(d^{1/4})$. Next chapter: SVD, can do with $\Omega(1)$ S.D.'s

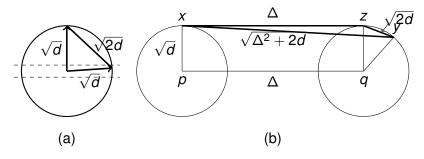


Figure: (a) indicates that two randomly chosen points in high dimension are surely almost nearly orthogonal. (b) indicates that the distance between a pair of random points from two different unit balls approximating the annuli of two Gaussians.

• If **x**, **y** are two (indep) samples from the first Gaussian, then:

$$|\mathbf{x} - \mathbf{y}|^2 = |\mathbf{x}|^2 + |\mathbf{y}|^2 - 2\mathbf{x} \cdot \mathbf{y} = (d \pm O(\sqrt{d})) + (d \pm O(\sqrt{d})) \pm O(\sqrt{d}) = 2d \pm O(\sqrt{d}).$$

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 If the two centers are Δ apart and x, z are respectively from the two Gaussians, then

$$|\mathbf{x} - \mathbf{z}|^2 = |(\mathbf{x} - \mu_1) + (\mu_1 - \mu_2) + (\mu_2 - \mathbf{z})|^2 = d \pm O(\sqrt{d}) + \Delta^2 + d \pm \sqrt{d} + d$$

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- If we want all pair of points to behave well (union bound) suffices to have $\Delta > cd^{1/4}\sqrt{\ln n}$.