

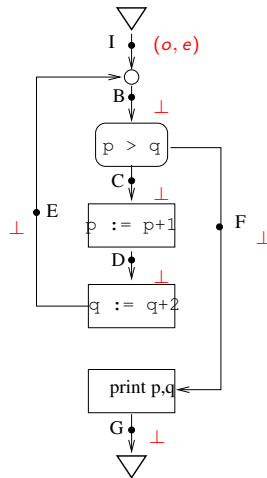
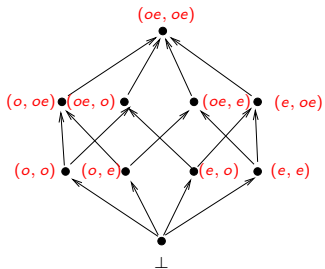
Kildall's algorithm for over-approximate JOP

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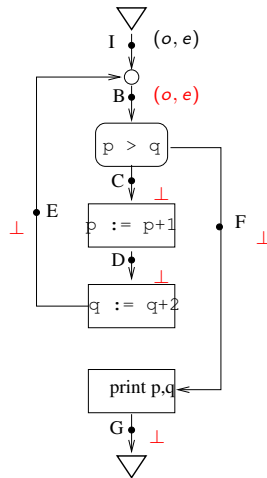
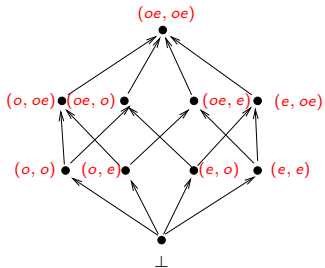
Kildall's algo on parity interpretation example

Underlying lattice



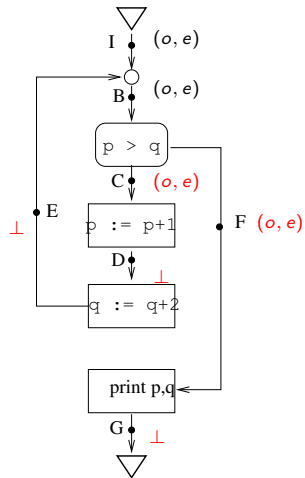
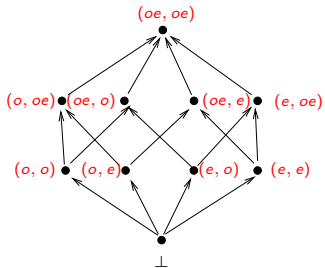
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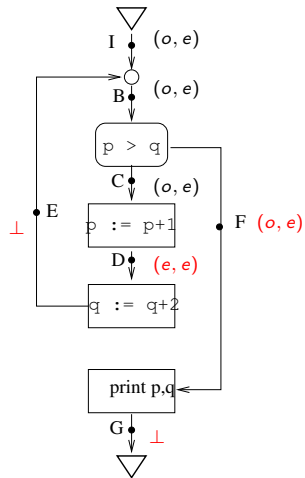
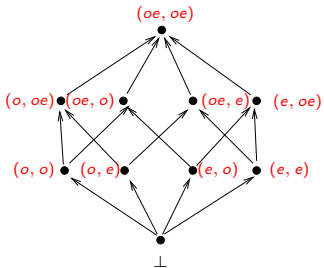
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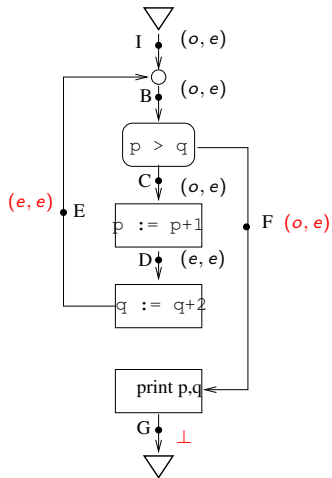
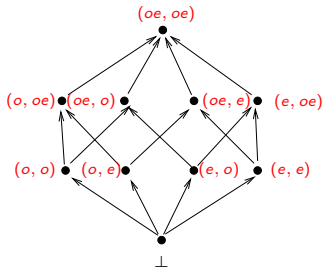
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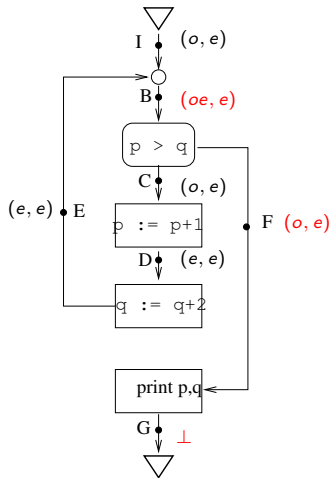
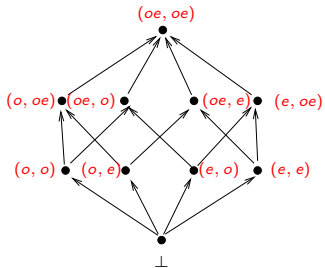
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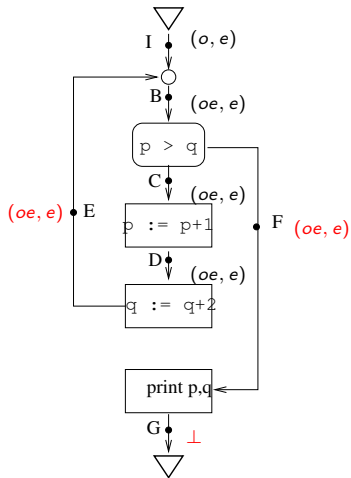
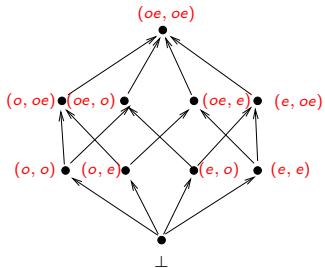
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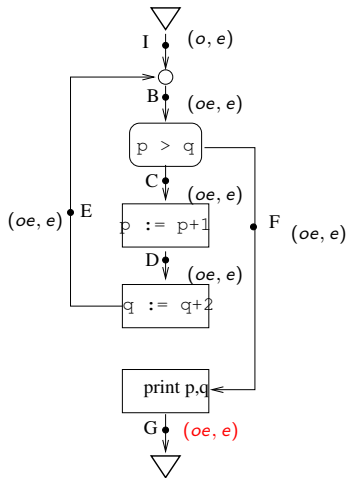
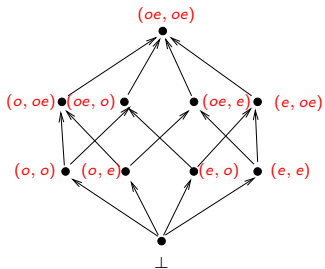
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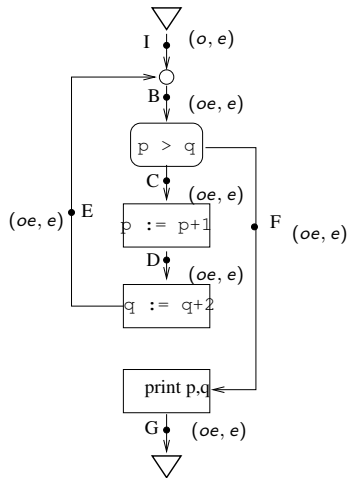
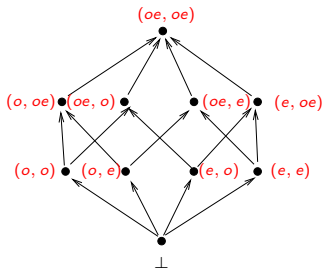
Kildall's algo on parity interpretation example

Underlying lattice



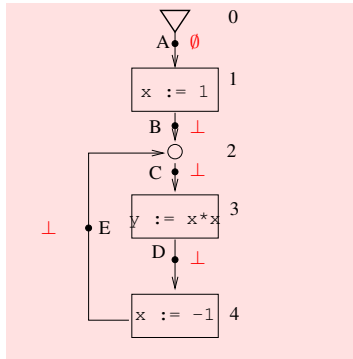
Kildall's algo on parity interpretation example

Underlying lattice

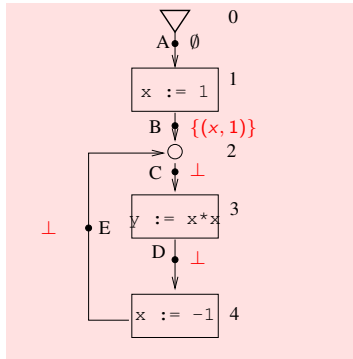


Values computed coincide with JOP values.

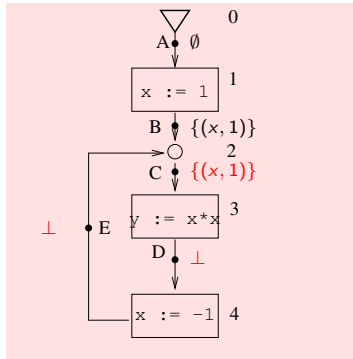
Kildall's algo on CP example: 1



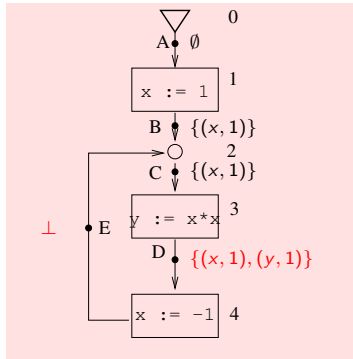
Kildall's algo on CP example: 2



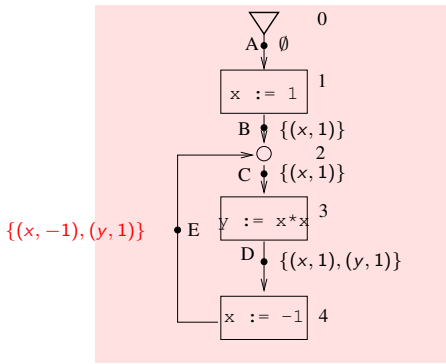
Kildall's algo on CP example: 3



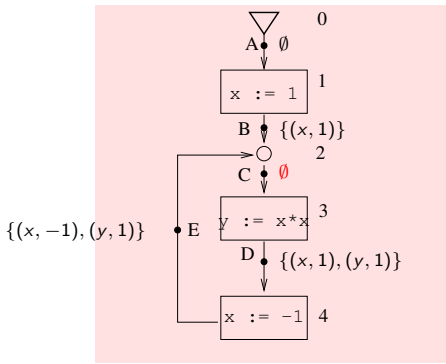
Kildall's algo on CP example: 4



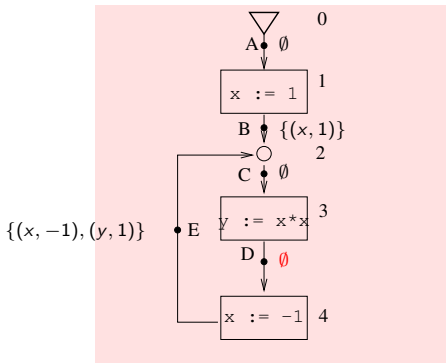
Kildall's algo on CP example: 5



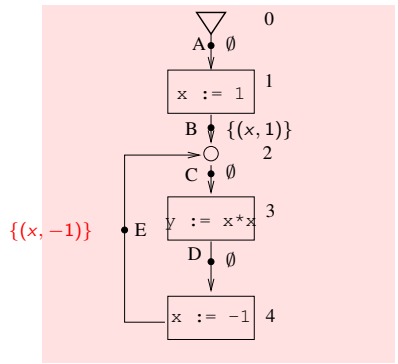
Kildall's algo on CP example: 6



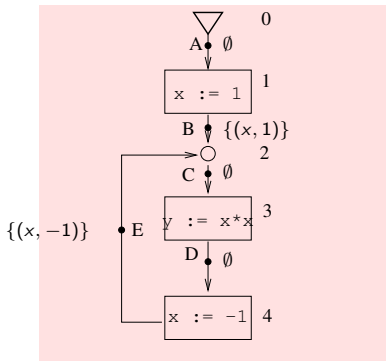
Kildall's algo on CP example: 7



Kildall's algo on CP example: 8

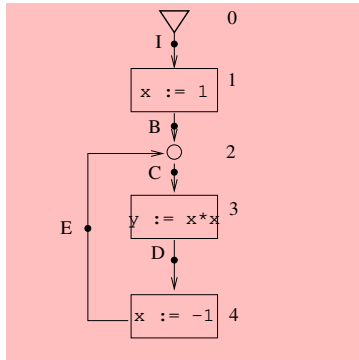


Kildall's algo on CP example: 9



Kildall's algo vs Actual Constant data

ProgPt	Actual JOP values	Kildall's data
A	\emptyset	\emptyset
B	$\{(x, 1)\}$	$\{(x, 1)\}$
C	\emptyset	\emptyset
D	$\{(y, 1)\}$	\emptyset
E	$\{(x, -1), (y, 1)\}$	$\{(x, -1)\}$



Note that Kildall's values are \geq the actual JOP values at all points.

What Kildall's algo computes

- Always terminates if lattice has no infinite ascending chains.
- In general, computes the least solution to a system of equations induced by the given instance of the analysis.
- This value is always an **over-approximation** of the JOP for the given instance.

Induced Equations

The program induces a set of **data-flow equations**:

$$\begin{aligned}x_I &= d_0 && \text{for entry point } I \\x_N &= f_{MN}(x_M) && \text{for an assignment or conditional node } n \text{ with} \\ &&& \text{with incoming point } M \text{ and outgoing point } N \\x_N &= x_L \sqcup x_M && \text{for a junction node with incoming points } L, M \\ &&& \text{and outgoing } N. \\ \dots &&& \text{etc.}\end{aligned}$$

Induced Equations

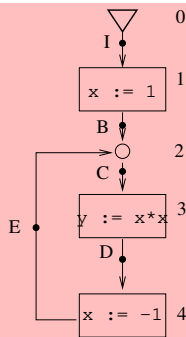
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Note: The collecting semantics is a solution to the above equations.

Example equations

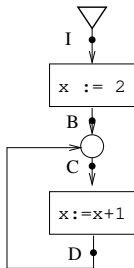
$$\begin{aligned}x_I &= \emptyset (= d_0) \\x_B &= f_1(x_I) \\x_C &= x_B \sqcup x_E \\x_D &= f_3(x_C) \\x_E &= f_4(x_D).\end{aligned}$$



Equations can have multiple solutions

Exercise: Give two solutions to equations induced for this program

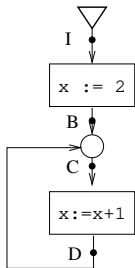
- Use lattice of subsets of concrete stores, with integer values for x .
- Write down induced equations.
- Give **two** different solutions to the equations.



Equations can have multiple solutions

Exercise: Give two solutions to equations induced for this program

- Use lattice of subsets of concrete stores, with integer values for x .
- Write down induced equations.
- Give **two** different solutions to the equations.



Note: collecting semantics of any program is the **least solution** to its data-flow equations using the concrete lattice (to be shown).

Function \bar{f} induced by equations

Equations:

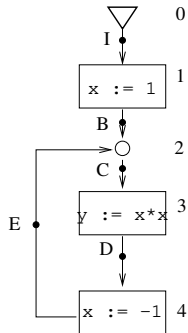
$$x_I = \emptyset (= d_0)$$

$$x_B = f_1(x_I)$$

$$x_C = x_B \sqcup x_E$$

$$x_D = f_3(x_C)$$

$$x_E = f_4(x_D).$$

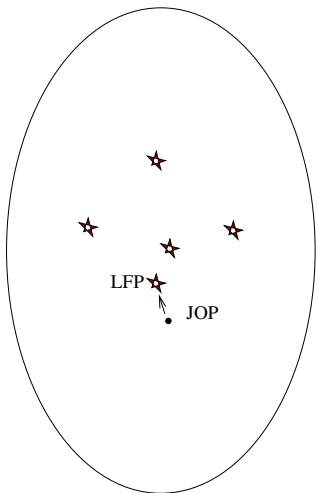
Corresponding \bar{f} function:

$$\bar{f}(d_I, d_B, d_C, d_D, d_E) = (d_0, f_1(d_I), d_B \sqcup d_E, f_3(d_C), f_4(d_D)).$$

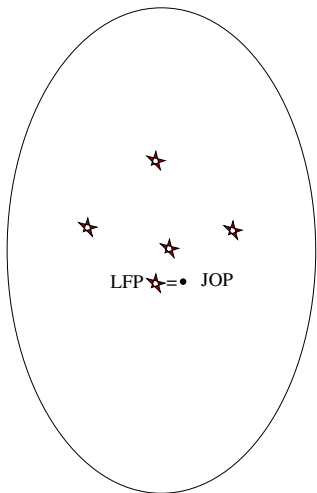
Natural ordering on solutions to Eq

- Consider “vectorised” lattice $\overline{D} = (D^k, \underline{\leq})$, where D is the underlying lattice.
- Each solution to the equations is a point in this vectorised lattice.
- The solutions are **precisely** the fix-points of the function $\overline{f}: \overline{D} \rightarrow \overline{D}$.
- **If** D is a complete lattice and f_i 's are monotone, **then** \overline{D} is complete and \overline{f} is monotone.
 - Note: Concrete analysis satisfies these properties. So do many abstract interpretations.
- Therefore, **Knaster-Tarski** theorem applies. Therefore, there exists a **least** solution to \overline{f} .
- Kildall's algorithm computes this lfp (if it terminates).
 - So does the Kleene iteration $\perp_{\overline{D}}, \overline{f}(\perp_{\overline{D}}), \overline{f}^2(\perp_{\overline{D}}), \dots$ if it reaches a stable value.

Correctness



Monotonic Framework

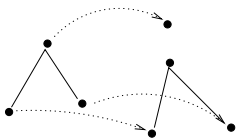


Infinitely-Distributive Framework

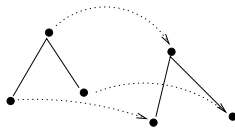
$(\bar{D}, \bar{\leq})$

Kildall's algo always computes LFP of \bar{f} .

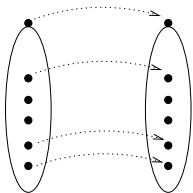
Monotonicity, distributivity, and continuity



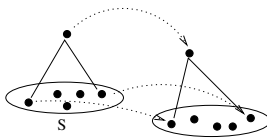
Monotonic



Distributive



Continuous



Inf-Distributive
(S is any subset of the lattice,
including empty subset, or an infinite subset)

1. JOP \leq LFP for monotone framework

- Let \bar{c} be any FP of \bar{f} . Consider any program point N . Let $c_N \equiv \bar{c}[N]$.
- **Claim:** For any path p , if N is the point at the end of p , c_N dominates $d \equiv f_p(d_0)$ reaching N .

The argument is by induction on length of path p .

- Base case $|p| = 0$: Then $N = I$, and $d = c_N = d_0$.
- Let path p be of length $i + 1$. Let M be the program that p passes through just before reaching N . Let d' be $f_p^M(d_0)$, where f_p^M is the path transfer function of the prefix of path p that ends at point M . The inductive hypothesis is that $d' \sqsubseteq c_M$.

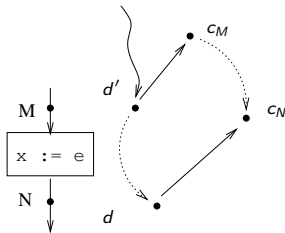
The rest of the proof is in two cases.

1. JOP \leq LFP for monotone framework

Case (node between M and N is not a join node):

By definition of \bar{f} , $(\bar{f}(\bar{c}))[N] = f_{MN}(c_M)$. Now, since \bar{c} is an FP of \bar{f} , $c_N = (\bar{f}(\bar{c}))[N]$. Therefore, $c_N = f_{MN}(c_M)$.

Now, since $d = f_{MN}(d')$, by monotonicity of f_{MN} , and from the hypothesis $d' \sqsubseteq c_M$, it follows that $d \sqsubseteq c_N$.



1. JOP \leq LFP for monotone framework

Case (node between M and N is a join node):

Let P be the other predecessor of the join node.

- 1 $d = d'$ (because join nodes have identity transfer function)
- 2 $c_M \sqsubseteq c_N$. The argument for this is as follows. By definition of \bar{f} , $(\bar{f}(\bar{c}))[N] = c_M \sqcup c_P$. Now, since \bar{c} is an FP of \bar{f} , $c_N = (\bar{f}(\bar{c}))[N]$. Therefore, $c_N = c_M \sqcup c_P$.

The two observations above in conjunction with the inductive hypothesis imply that $d \sqsubseteq c_N$.

1. JOP \leq LFP for monotone framework

- That is, for every path p that reaches a point N , $f_p(d_0) \sqsubseteq c_N$.
- Therefore, JOP d_N at N is $\sqsubseteq c_N$

2. JOP = LFP for infinitely-distributive framework

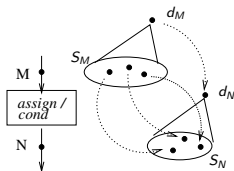
Proof: Enough to show that the JOP \bar{d} is a fixpoint of \bar{f} . We denote $\bar{d}[M]$ as d_M , $\bar{d}[N]$ as d_N , etc.

2. JOP = LFP for infinitely-distributive framework

Proof: Enough to show that the JOP \bar{d} is a fixpoint of \bar{f} . We denote $\bar{d}[M]$ as d_M , $\bar{d}[N]$ as d_N , etc.

Let N be any program point.

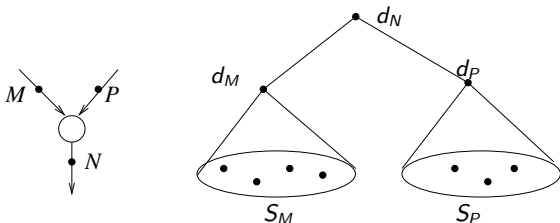
Case (the node before N is not a join node):



- Let S_M (resp. S_N) be the set of all facts that reach M (resp. N) along all paths.
- It is clear that $S_N = \{f_{MN}(s) | s \in S_M\}$.
- It is clear that the JOP d_M at M is equal to $\sqcup S_M$, and the JOP d_N at N is equal to $\sqcup S_N$.
- Therefore, by the previous two observations, and due to infinite distributivity, it follows that $d_N = f_{MN}(d_M)$.
- Therefore, \bar{d} satisfies N 's equation, which is $x_N = f_{MN}(x_M)$.

2. JOP = LFP for infinitely-distributive framework

Case (the node before N is a join node):



- Say S_M (resp. S_P resp. S_N) is the set of lattice values reaching M along all paths (resp. reaching P resp. reaching N).
- Clearly, d_M (resp. d_P resp. d_N) is equal to $\sqcup S_M$ (resp. $\sqcup S_P$ resp. $\sqcup S_N$).
- It is clear that $S_N = S_M \cup S_P$. Therefore, $d_N = d_M \sqcup d_P$.
- Therefore, \bar{d} satisfies N 's equation, which is $x_N = x_M \sqcup x_P$.

2. JOP = LFP for infinitely-distributive framework

- Since the argument in the previous two slides applies at all points N , we have shown that the vector \bar{d} satisfies all the equations, and is hence a fix-point of \bar{f} .
- Note: Lattice is finite, and functions are pairwise distributive, and $f_i(\perp) = \perp$ **implies** framework is infinitely distributive.

Back to Constant Propagation

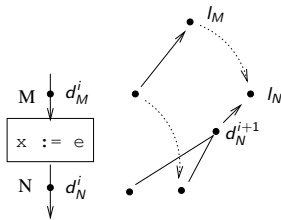
- f_n^{CP} is monotonic
- f_n^{CP} is *not* distributive.
 - Consider node n with statement $y := x * x$, and abstract states $P_1 = \{(x, 1)\}$ and $P_2 = \{(x, -1)\}$.
 - Since $P_1 \sqcup P_2$ is \top , $f_n(P_1 \sqcup P_2) = \top$
 - On the other hand, $f_n(P_1) \sqcup f_n(P_2) = \{(y, 1)\}$.
- The $nstate'$ functions are all distributive.

3. Kildall's algo computes LFP

- Let \bar{d} be values computed by Kildall's algo upon termination, and \bar{l} be LFP of \bar{f} . Let l_N denote $\bar{l}[N]$, l_M denote $\bar{l}[M]$, etc.
- Intermediate vector \bar{d}^i after any step i is bounded above by \bar{l} . We prove this using induction on number of steps.
- Let N be any program point whose value gets updated in Step $i + 1$.

3. Kildall's algo computes LFP

Case (the node before N is a non-join node):



Explanation:

- $d_M^i \sqsubseteq l_M$ and $d_N^i \sqsubseteq l_N$ by inductive hypothesis.
- $l_N = f_{MN}(l_M)$, because \bar{l} is a solution to the equations and because we have the equation $x_N = f_{MN}(x_M)$.
- Therefore, due to monotonicity of f_{MN} , $f_{MN}(d_M^i) \sqsubseteq l_N$.
- Since $d_N^{i+1} = d_N^i \sqcup f_{MN}(d_M^i)$, we derive $d_N^{i+1} \sqsubseteq l_N$.

3. Kildall's algo computes LFP

Case (the node before N is a join node):

- Let M and P be the points that precede the join node. Let d_M^i, d_P^i, d_N^i be the data values at the respective program points after Step i .
- Say propagation happens from M to N in Step i (argument is similar if propagation happened from P to N).
- Since \bar{l} is a solution to the equations, and since we have the equation $x_N = x_M \sqcup x_P$, it follows that $l_N = l_M \sqcup l_P$. In other words, $l_M \sqsubseteq l_N$. In conjunction with $d_M^i \sqsubseteq l_M$ (inductive hypothesis), we get $d_M^i \sqsubseteq l_N$.
- By inductive hypothesis, $d_N^i \sqsubseteq l_N$. Therefore, $(d_N^{i+1} = (d_M^i \sqcup d_N^i)) \sqsubseteq l_N$.

Thus it follows that $\bar{d} \leq \bar{l}$.

3. Kildall's algo computes LFP

Let \bar{d} be the vector computed by the algorithm upon termination.
We now show that $\bar{d} \geq \bar{f}(\bar{d})$ (i.e. \bar{d} is a postfixpoint of \bar{f})

Let N be any program point.

Case (the node before N is a non-join node):

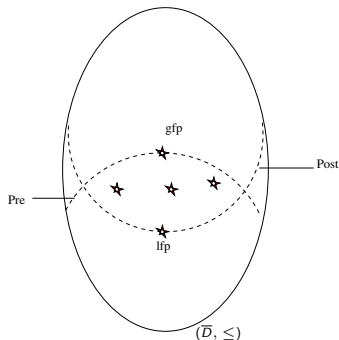
- Let M be the point that precedes this node. By definition of \bar{f} , $(\bar{f}(\bar{d}))[N]$ is equal to $f_{MN}(d_M)$.
- Since all points are unmarked, value d_M must have been propagated to N . That is, d_N must dominate $f_{MN}(d_M)$. That is, d_N dominates $(\bar{f}(\bar{d}))[N]$.

Case (the node before N is a join node):

- Let M and P be the points that precede the join node. By definition of \bar{f} , $(\bar{f}(\bar{d}))[N]$ is equal to $d_M \sqcup d_P$.
- Since all points are unmarked, value d_M and d_P must have been propagated to N . That is, d_N must dominate both d_M and d_P . That is, d_N dominates $d_M \sqcup d_P$. Hence, d_N dominates $(\bar{f}(\bar{d}))[N]$.

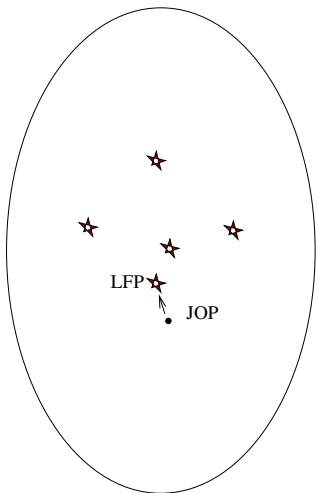
3. Kildall's algo computes LFP

- Therefore, by Knaster-Tarski theorem, $\bar{l} = glb(Post)$, and hence $\bar{d} \geq \bar{l}$.

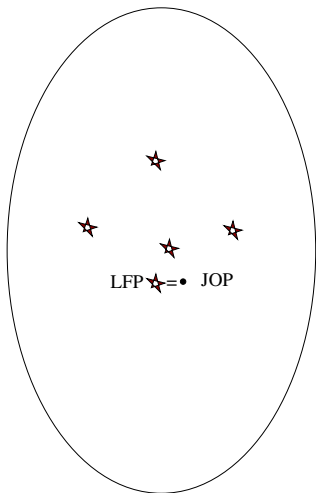


- We have earlier proved that $\bar{d} \leq \bar{l}$. Therefore, it follows that $\bar{d} = \bar{l}$.

Correctness



Monotonic Framework



Infinitely-Distributive Framework

$(\bar{D}, \bar{\leq})$

Kildall's algo always computes LFP.

Overview of correctness

- Every program induces a set of equations on variables whose domain is lattice D . The equations, in turn, induce a function $\bar{f} : \bar{D} \rightarrow \bar{D}$.
- **If** each f_i is monotone and D is a complete lattice **then** \bar{f} has a least fix-point $\text{LFP}(\bar{f})$.
 - If each f_i is infinitely distributive, then $\text{JOP} = \text{LFP}(\bar{f})$.
 - Otherwise, if each f_i is only monotonic, $\text{JOP} \leq \text{LFP}(\bar{f})$.

Overview of correctness

- Every program induces a set of equations on variables whose domain is lattice D . The equations, in turn, induce a function $\bar{f} : \bar{D} \rightarrow \bar{D}$.
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 - If each f_i is infinitely distributive, then $\text{JOP} = \text{LFP}(\bar{f})$.
 - Otherwise, if each f_i is only monotonic, $\text{JOP} \leq \text{LFP}(\bar{f})$.
- Kildall's algorithm, for monotone frameworks:
 - Solution *at any point* during its execution is $\leq \text{LFP}(\bar{f})$
 - If and when it terminates, solution is equal to $\text{LFP}(\bar{f})$
 - Note this is a stronger claim than "Kildall's algo computes JOP for distributive frameworks" [Kildall, 'POPL 73].
 - Kildall's algorithm is not only for program analysis. It can be used to find least solution to *any* set of simultaneous equations, as long as (a) domain of variables' values is a complete lattice, (b) each variable occurs in the lhs of a unique equation, and (c) all operators occurring in rhs's are monotone.

Summary of sufficient conditions

	Termination	$LFP \geq JOP$	$LFP = JOP$	Kild computes LFP upon termination
f_{MN} 's monotonic No inf. asc. chains Inf. distributive	✓ ✓	✓	✓	✓

- Each column is a property, and each row is a sufficient condition
- For a property to hold, *each* sufficient condition mentioned in its column needs to hold