

An Optimizing Code Generator for a Class of Lattice-Boltzmann Computations

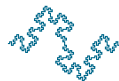
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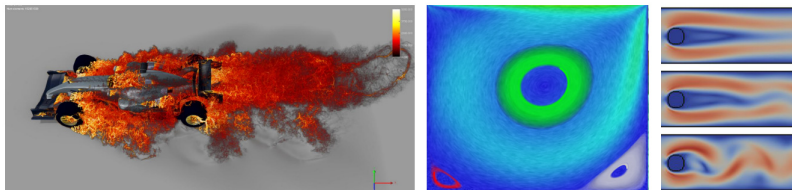
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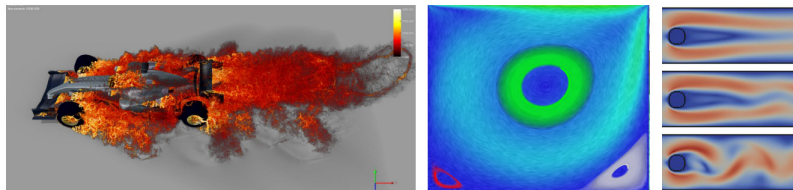


INTRODUCTION



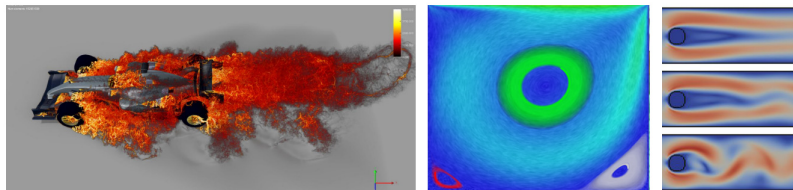
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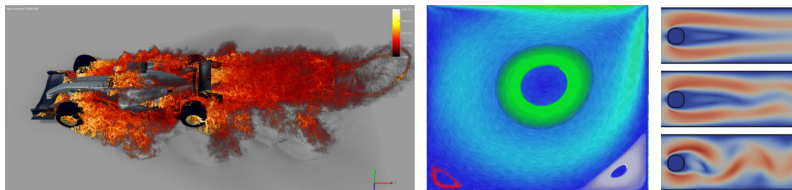
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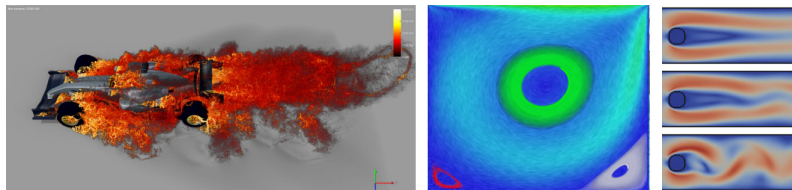
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- ▶ Particularly suited for parallel and high performance implementations
- ▶ In spite of tremendous advances in its application, several fundamental opportunities for optimization remain
- ▶ We explore one such opportunity through this work

LATTICE-BOLTZMANN METHOD

- ▶ Fluid flows are modelled as hypothetical particles
 - ▶ moving in a lattice domain (discretized space)
 - ▶ with different lattice velocities (discretized momentum)
 - ▶ over different time steps (discretized time)

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 - ▶ with different lattice velocities (discretized momentum)
 - ▶ over different time steps (discretized time)
- ▶ Solves the discrete Boltzmann equation for the particle distribution function (a probability density function)

LBM - LATTICE ARRANGEMENTS

- ▶ Lattice arrangements are represented as $DmQn$
 - ▶ m is the space dimensionality of the lattice
 - ▶ n is the number of PDFs (or speeds) involved

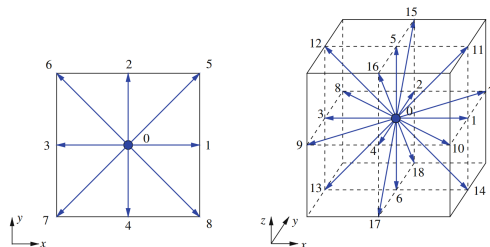


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- ▶ Choice of lattice affects precision and duration of simulation

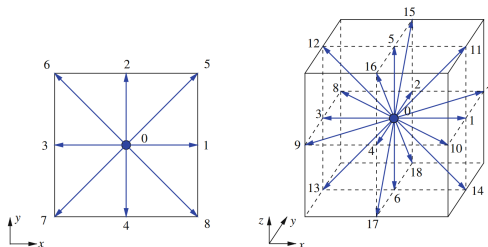


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LATTICE-BOLTZMANN METHOD

- The discretized form of Lattice-Boltzmann Equation forms the basis of all LBM models

$$f_i(\mathbf{x} + \mathbf{c}_i \Delta t, t + \Delta t) = f_i(\mathbf{x}, t) + \Omega_i(f_i(\mathbf{x}, t)), \quad i = 1, \dots, n. \quad (1)$$

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- Eqn. 1 is solved in two steps, the **collision** step (Eqn. 2) & the **advection** step (Eqn. 3)

$$f_i^*(\mathbf{x}, t + \Delta t) = f_i(\mathbf{x}, t) + \Omega_i(f_i(\mathbf{x}, t)) \quad (2)$$

$$f_i(\mathbf{x} + \mathbf{c}_i \Delta t, t + \Delta t) = f_i^*(\mathbf{x}, t + \Delta t) \quad (3)$$

LBM - IMPLEMENTATION STRATEGIES

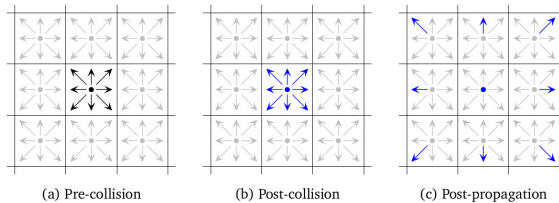


Figure: Push Scheme

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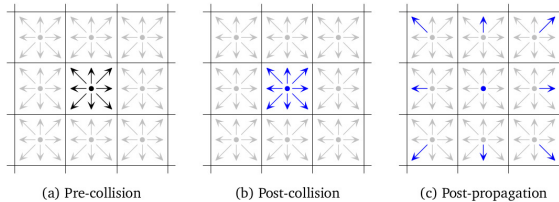


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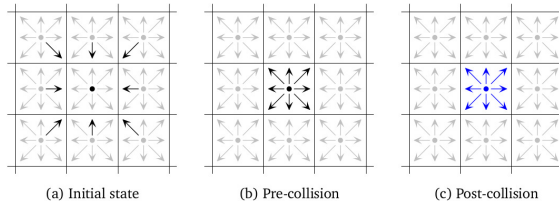


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MOTIVATION

To build a comprehensive framework that can address shortcomings of previous works and automatically generate high performance code for LBM simulations

► Related work

- Wilke et al. - *Euro-Par 2003* - 1D & 2D blocking
- Nitsure et al. - *FIS 2006* - Cache oblivious algorithm for LBM
- Nguyen et al. - *SC 2010* - 3.5D Blocking
- Palabos - an open-source CFD solver based on the Lattice Boltzmann method (library-based)

Is it possible to optimize LBM using
time tiling?

TILING (BLOCKING)

- Partition and execute iteration space in blocks

```
for(i=1; i<T; i++)
  for(j=1; j<N-1; j++)
    S(i,j)
```

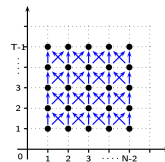


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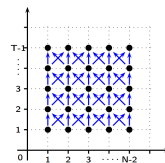


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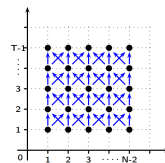


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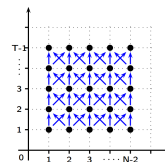


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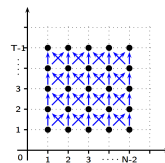


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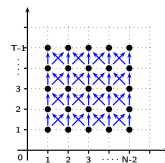


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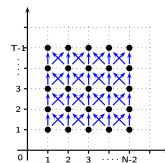


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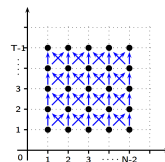


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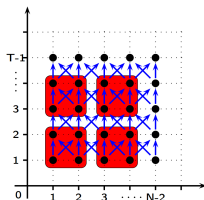


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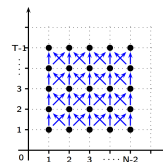


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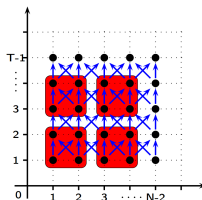


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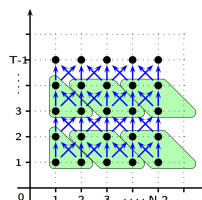


Figure: Valid tiling

CONCURRENT START AND DIAMOND TILING¹

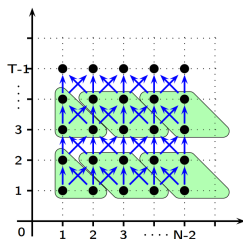


Figure: Parallelogram tiling

¹Tiling Stencil Computations to Maximize Parallelism, *Vinayaka Bandishti, Irshad Pananilath, and Uday Bondhugula*, ACM/IEEE Supercomputing (SC) 2012

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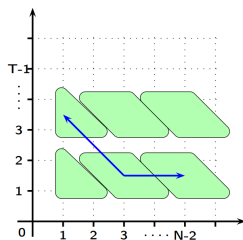


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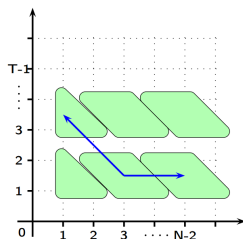


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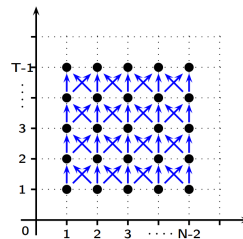


Figure: Original iteration space

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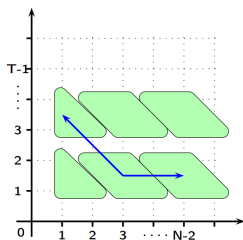


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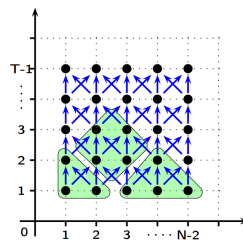


Figure: Group as diamonds

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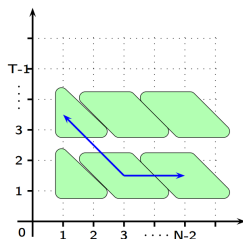


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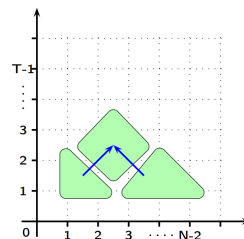


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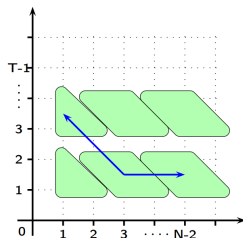


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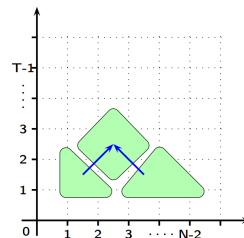


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 - ▶ Face allowing concurrent should be strictly within the cone of the tiling hyperplanes
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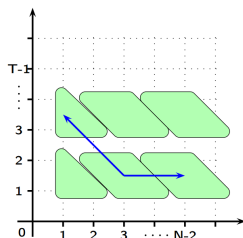


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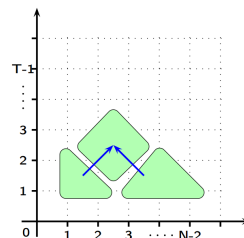


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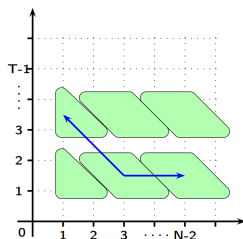


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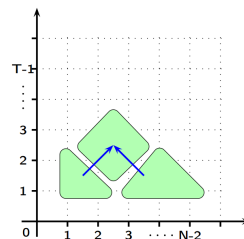


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- ▶ Improvement of 4% to 27% over a domain-specific compiler (Pochoir) on 12 cores

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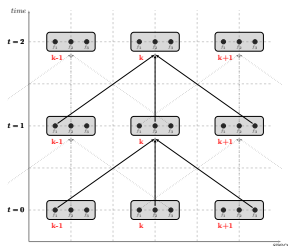


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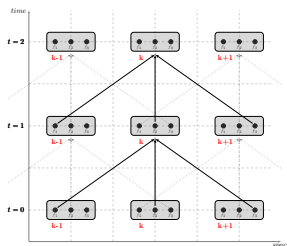


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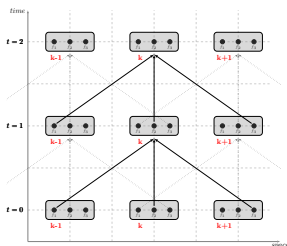


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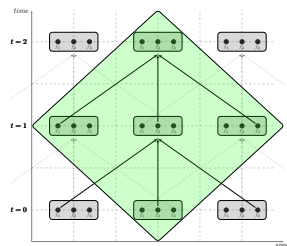


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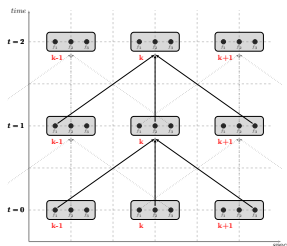


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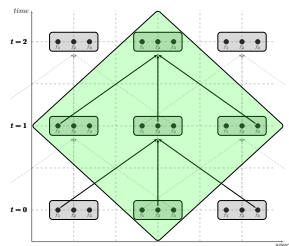


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- Not possible to *“time tile”* LBM with single grid
- Time tiling is possible with two grids

msLBM - LBM OPTIMIZATION FRAMEWORK

- ▶ We utilize a fused version of the LBM kernel
 - ▶ No explicit *advection* phase
 - ▶ 2 data grids with a pull scheme to read data
 - ▶ Array-of-Structures (AoS) layout for data

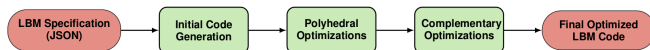


Figure: System Overview

¹JSON (JavaScript Object Notation) is a lightweight data-interchange format.

INPUT TO POLYHEDRAL TILER

```
#pragma scop
for (t = 0; t < _nTimesteps; t++)
  for (y = 2; y < _nY; y++)
    for (x = 1; x < _nX; x++)
      lbm_kernel(grid[t % 2][y][x][C],
                 grid[t % 2][y - 1][x + 0][N],
                 grid[t % 2][y + 1][x + 0][S],
                 grid[t % 2][y + 0][x - 1][E],
                 grid[t % 2][y + 0][x + 1][W],
                 grid[t % 2][y - 1][x - 1][NE],
                 grid[t % 2][y - 1][x + 1][NW],
                 grid[t % 2][y + 1][x - 1][SE],
                 grid[t % 2][y + 1][x + 1][SW],

                 &grid[(t + 1) % 2][y][x][C],
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                 &grid[(t + 1) % 2][y][x][E],
                 &grid[(t + 1) % 2][y][x][W],
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                 &grid[(t + 1) % 2][y][x][SE],
                 &grid[(t + 1) % 2][y][x][SW], t, y, x);
```

- ▶ Use the **PET polyhedral frontend** [Verdoolaeye and Grosser 2012]: the LBM collision is treated as a blackbox (abstracted as a single function)
- ▶ Dependence structure is now similar to “toy time-iterated stencils”
- ▶ **All time tiling strategies can now be applied!**

COMPLEMENTARY OPTIMIZATIONS

Simplification of the LBM Kernel

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Simplification of the LBM Kernel

- ▶ In most cases, the compiler is not able to simplify the LBM kernel to remove common expressions
- ▶ We perform common sub-expression elimination using **Python SimPy** on the composed LBM kernel
 - ▶ reduces the number of FP-ops required for LBM kernel execution

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Alignment, Vectorization, Inlining & Unrolling

- ▶ For the polyhedral optimization part, the LBM compute kernel was treated as a blackbox function
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- ▶ Perform structuring to improve vectorizability
 - ▶ Generate data alignment directives
 - ▶ Unroll the LBM kernel by a suitable factor

COMPLEMENTARY OPTIMIZATIONS

Boundary Tile Separation

- ▶ **Boundary conditions:** *in-domain* tiles and *boundary* tiles
- ▶ LBM requires special treatment for the boundary tiles of the domain
 - ▶ results in *IF* conditions inside the LBM kernel to identify and handle boundaries separately
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 - ▶ results in degraded performance for the vast number of in-domain tiles
- ▶ We identify and generate different LBM kernels for boundary and in-domain tiles
- ▶ In-domain LBM kernel can be both unrolled and inlined for better performance

EXPERIMENTAL SETUP

Intel Xeon E5-2680 (SandyBridge)	
Clock	2.7 GHz
Cores / socket	8
Total cores	16
L1 cache / core	32 KB
L2 cache / core	512 KB
L3 cache / socket	20 MB
Peak GFLOPs	172.8
Compiler	Intel C compiler (icc) 14.0.1
Compiler flags	-O3 -xHost -ipo -fno-alias -fno-fnalias -restrict -fp-model precise -fast-transcendentals
Linux kernel	3.8.0-38

Table: Architecture details

- We compare the performance of our framework on 7 benchmarks against
 - Palabos - an open-source CFD solver based on LBM
 - Compiler auto-parallelization [*icc-auto-par*]
 - Naive manual parallelization using OpenMP [*icc-omp-par*]

BENCHMARKS

- ▶ Lid Driven Cavity - d2q9, d3q19 and d3q27

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- ▶ Flow Past Cylinder - d2q9
- ▶ MRT - GLBM - d2q9

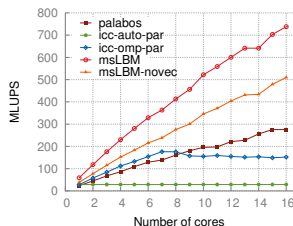
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- ▶ Lid Driven Cavity - d2q9, d3q19 and d3q27
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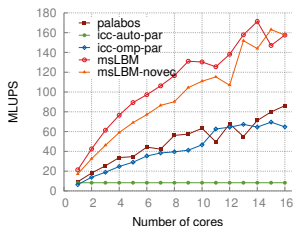
Performance Metrics

- ▶ MLUPS - Million Lattice site Updates Per Second
- ▶ MEUPS - Million Element Updates Per Second

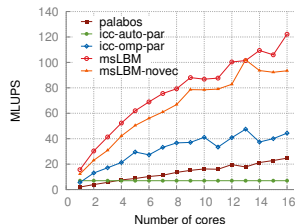
PERFORMANCE - LDC



(a) ldc-d2q9

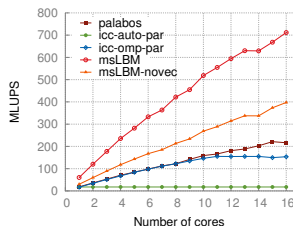


(b) ldc-d3q19

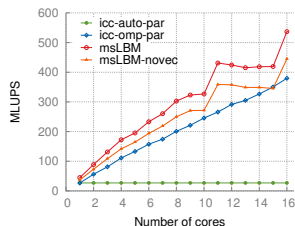


(c) ldc-d3q27

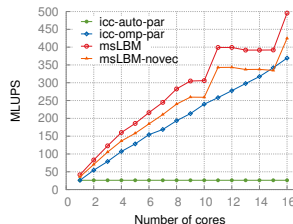
PERFORMANCE - MRT, POISEUILLE, FPC



(a) mrt-d2q9

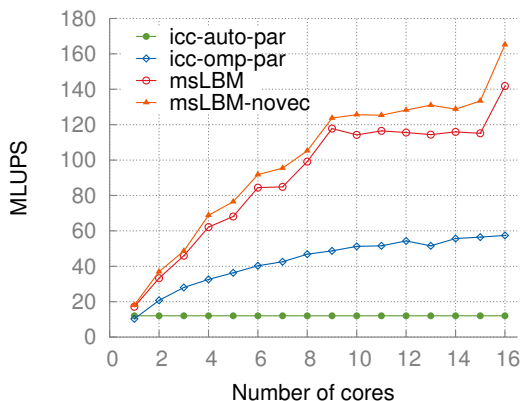


(b) poiseuille



(c) fpc-d2q9

PERFORMANCE - SPEC LBM



(a) spec - lbm performance

- D3Q19 lattice with an ellipsoid obstacle in the grid
- An improvement of 2.47x

ROOFLINE PERFORMANCE MODEL

- Computational characteristics of numerical methods can vary dramatically

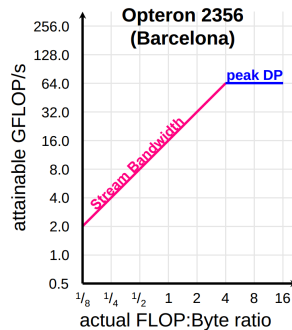


Figure: Basic roofline plot

ROOFLINE PERFORMANCE MODEL

- ▶ Computational characteristics of numerical methods can vary dramatically
- ▶ Goal: integrate in-core performance, memory bandwidth, and locality into a single readily understandable performance figure

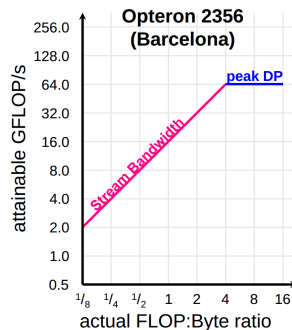


Figure: Basic roofline plot

ROOFLINE PERFORMANCE MODEL - CONTD.

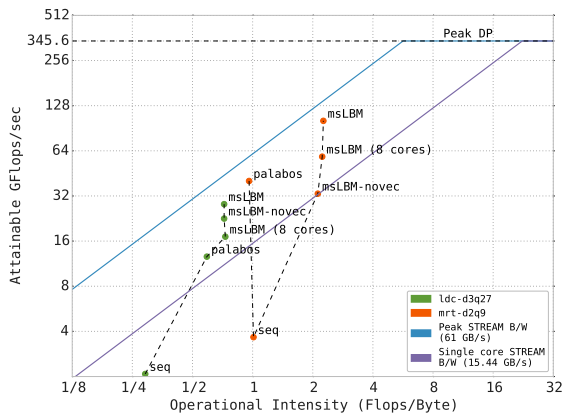


Figure: Roofline model for mrt-d2q9 & ldc-d3q27

ROOFLINE PERFORMANCE MODEL - CONTD.

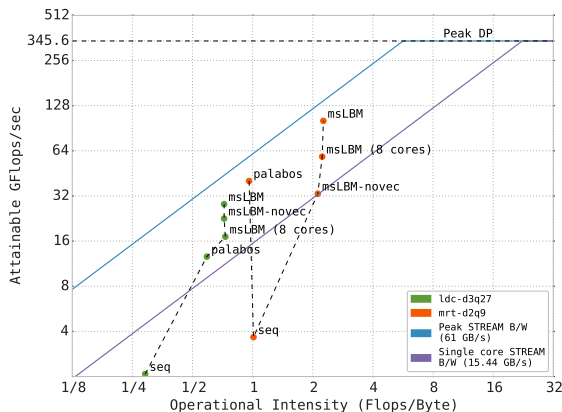


Figure: Roofline model for mrt-d2q9 & ldc-d3q27

- msLBM obtains further improvement over Palabos in both operational intensity and peak achievable performance

RESULTS - SUMMARY

- ▶ Our scheme consistently outperformed Palabos on average by $3\times$ on 16 cores of an Intel Sandybridge system
- ▶ A significant improvement of $2.47\times$ over the best native production compiler for SPEC LBM benchmark
- ▶ msLBM obtains improvement over Palabos in both operational intensity and sustained performance

CONCLUSIONS AND FUTURE WORK

- ▶ Proposed a domain-specific framework to generate optimized code for LBM computations
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- ▶ Reasoned about automatic time tiling for LBM kernels
- ▶ Significant improvements in various cases
- ▶ Characterized LBM performance with the Roofline model
- ▶ Implemented the system using PET, Pluto and Python Sym
- ▶ **Future:** Integrate with DSL frontend of PolyMage [Mullapudi et al ASPLOS 2015]

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Thank You!